

Contents

Introduction to Part II	v
Chapter 7. STRUCTURALLY STABLE SYSTEMS	393
7.1. Rough systems on a plane. Andronov–Pontryagin theorem	394
7.2. The set of center motions	399
7.3. General classification of center motions	404
7.4. Remarks on roughness of high-order dynamical systems	409
7.5. Morse–Smale systems	412
7.6. Some properties of Morse–Smale systems	419
Chapter 8. BIFURCATIONS OF DYNAMICAL SYSTEMS	429
8.1. Systems of first degree of non-roughness	430
8.2. Remarks on bifurcations of multi-dimensional systems	437
8.3. Structurally unstable homoclinic and heteroclinic orbits. Moduli of topological equivalence	440
8.4. Bifurcations in finite-parameter families of systems. Andronov’s setup	444
Chapter 9. THE BEHAVIOR OF DYNAMICAL SYSTEMS ON STABILITY BOUNDARIES OF EQUILIBRIUM STATES	451
9.1. The reduction theorems. The Lyapunov functions	452

9.2.	The first critical case	458
9.3.	The second critical case	465
Chapter 10.	THE BEHAVIOR OF DYNAMICAL SYSTEMS ON STABILITY BOUNDARIES OF PERIODIC TRAJECTORIES	475
10.1.	The reduction of the Poincaré map. Lyapunov functions	475
10.2.	The first critical case	480
10.3.	The second critical case	489
10.4.	The third critical case. Weak resonances	493
10.5.	Strong resonances	500
10.6.	Passage through strong resonance on stability boundary	515
10.7.	Additional remarks on resonances	527
Chapter 11.	LOCAL BIFURCATIONS ON THE ROUTE OVER STABILITY BOUNDARIES	531
11.1.	Bifurcation surface and transverse families	531
11.2.	Bifurcation of an equilibrium state with one zero exponent	537
11.3.	Bifurcation of periodic orbits with multiplier $+1$	559
11.4.	Bifurcation of periodic orbits with multiplier -1	578
11.5.	Andronov–Hopf bifurcation	598
11.6.	Birth of invariant torus	611
11.7.	Bifurcations of resonant periodic orbits accompanying the birth of invariant torus	623
Chapter 12.	GLOBAL BIFURCATIONS AT THE DISAPPEARANCE OF SADDLE-NODE EQUILIBRIUM STATES AND PERIODIC ORBITS	637
12.1.	Bifurcations of a homoclinic loop to a saddle-node equilibrium state	638
12.2.	Creation of an invariant torus	649
12.3.	The formation of a Klein bottle	666

12.4.	The blue sky catastrophe	670
12.5.	On embedding into the flow	681
Chapter 13.	BIFURCATIONS OF HOMOCLINIC LOOPS OF SADDLE EQUILIBRIUM STATES	687
13.1.	Stability of a separatrix loop on the plane	688
13.2.	Bifurcation of a limit cycle from a separatrix loop of a saddle with non-zero saddle value	700
13.3.	Bifurcations of a separatrix loop with zero saddle value	712
13.4.	Birth of periodic orbits from a homoclinic loop (the case $\dim W^u = 1$)	720
13.5.	Behavior of trajectories near a homoclinic loop in the case $\dim W^u > 1$	745
13.6.	Codimension-two bifurcations of homoclinic loops	748
13.7.	Bifurcations of the homoclinic-8 and heteroclinic cycles	765
13.8.	Estimates of the behavior of trajectories near a saddle equilibrium state	789
Chapter 14.	SAFE AND DANGEROUS BOUNDARIES	801
14.1.	Main stability boundaries of equilibrium states and periodic orbits	802
14.2.	Classification of codimension-one boundaries of stability regions	804
14.3.	Dynamically definite and indefinite boundaries of stability regions	813
Appendix C:	Examples, Problems & Exercises	819
	Bibliography	927
	Index — Parts I & II	943