

Contents

1	Basic Concepts	1
1.1	Introduction	1
1.2	Magnet Types	2
1.3	Pictures	2
1.4	Conventions	6
1.5	The Field from a Line Current (Biot-Savart law)	6
1.6	Magnetic Force on a Line Current	7
1.6.1	MKS Units	7
1.6.2	Force Directions	8
1.6.3	Dipole Magnet	8
1.6.4	Quadrupole Magnet	8
1.6.5	Sextupole Magnet	9
1.6.6	Corrector Magnets	10
1.6.7	Specialized Magnets	11
1.6.8	More Polarity	14
1.6.9	Alternate Polarity Convention	15
1.7	Chapter Closure	15
1.8	Problems	17
2	Solutions of the Magnet Equations	19
2.1	Introduction	19
2.2	Maxwell's Magnet Equations	19
2.2.1	Continuity	19
2.2.2	Units	20
2.3	The Function of a Complex Variable	20
2.4	The Two-Dimensional Fields	21
2.4.1	Fields from the Two-Dimensional Function of a Complex Variable	22
2.5	Two Dimensional Fields in a Vacuum	22
2.5.1	Multipoles	22
2.5.2	Laplace's Equation	23
2.5.3	Solutions to Laplace's Equation	23

2.6	Two-Dimensional Vector and Scalar Potentials	24
2.6.1	Magnetic Fields from the Two-Dimensional Potentials	24
2.7	A Particular Function of the Complex Variable, $F = C_n z^n$	25
2.7.1	Ideal Two-Dimensional Multipole Magnets	26
2.7.2	Two-Dimensional Flux Lines and Poles	26
2.7.3	Pole Contours	30
2.7.4	Complex Extrapolation	30
2.8	Magnetic Fields Using the Function of the Complex Variable	31
2.8.1	$n=1$, the Dipole Magnet	32
2.8.2	$n=2$, the Quadrupole Magnet	32
2.8.3	$n=3$, the Sextupole Magnet	33
2.9	Multipole Errors	34
2.9.1	The Error Spectrum	34
2.9.2	“Allowed” or Systematic Multipole Errors	34
2.9.3	Multipole Field Errors	36
2.10	Simple Conformal Maps	37
2.10.1	Mapping Functions	37
2.10.2	Quadrupole to Dipole Map	38
2.10.3	Dipole to Quadrupole Map	38
2.10.4	Sextupole to Dipole Map	38
2.10.5	Dipole to Sextupole Map	39
2.10.6	Gradient Magnet to Dipole Map	39
2.10.7	Dipole to Gradient Magnet Map	40
2.11	Chapter Closure	40
2.12	Problems	41
3	Pole Tip Design	43
3.1	Understanding the Dipole Magnet	43
3.1.1	The Orthogonal Analog Model	43
3.1.2	The Orthogonal Analog Model and the Quadrupole	46
3.1.3	The “H” Dipole Geometry	48
3.1.4	H-Magnet Uniformity	50
3.2	Understanding the Quadrupole Magnet	53
3.2.1	Quadrupole Uniformity	53
3.3	Understanding the Gradient Magnet	56
3.3.1	Gradient Magnet Uniformity	56
3.4	Mapping an Existing Gradient Magnet Design	60
3.4.1	Baseline Optimized Pole	62
3.4.2	New Unoptimized Pole	63
3.4.3	Baseline Mapped Pole	63
3.4.4	New Mapped Unoptimized Pole	63
3.4.5	Scaling and Shifting	64

3.4.6	Center Expansion	65
3.4.7	Mapping Back into the Quadrupole Space	67
3.5	Chapter Closure	67
3.6	Problems	70
4	Perturbations	73
4.1	Introduction	73
4.2	Algorithms and Tables	74
4.2.1	Quadrupole Pole Error Coefficients, $N=2$	74
4.2.2	Sextupole Pole Error Pole Error Coefficients, $N=3$	75
4.2.3	Computing Error Multipoles	75
4.3	Two Piece Quadrupole	77
4.3.1	Magnet Assymetry	78
4.3.2	Differences in Lengths of the Upper and Lower Halves	80
4.3.3	Sorting	83
4.3.4	Two Piece Quadrupole Errors	83
4.3.5	Tolerances (Examples of Computations)	84
4.3.6	Alignment Error	85
4.3.7	Excitation Error	87
4.3.8	Random Multipole Error	87
4.4	Sextupole Trim Windings	89
4.4.1	Orthogonality	90
4.4.2	Horizontal Steering Trim	90
4.4.3	Vertical Steering and Skew Quadrupole Trim	91
4.4.4	Trim Excitations	93
4.5	Chapter Closure	94
4.6	Problems	96
5	Magnetic Excitation and Coil Design	97
5.1	Introduction	97
5.2	Maxwell's Inhomogeneous Equation	97
5.2.1	Continuity	98
5.3	Magnet Excitations	99
5.3.1	Magnet Efficiency	99
5.3.2	Dipole Magnets	100
5.3.3	Quadrupole Magnet	106
5.3.4	Sextupole Magnet	108
5.4	Coil Design	109
5.4.1	Coil Power	110
5.5	Coil Cooling	113
5.5.1	Pressure Drop	113
5.5.2	Flow Velocity	114

5.5.3	Units	115
5.5.4	Coil Cooling	119
5.5.5	Calculations	120
5.5.6	Sensitivities	121
5.6	Chapter Closure	126
5.7	Problems	128
6	POISSON	131
6.1	Elements of the Family of Codes	133
6.2	Documentation	134
6.3	Problem Flow	134
6.4	AutoMesh	136
6.4.1	Boundary Conditions and Constraints	136
6.4.2	Geometry	139
6.4.3	Setting Up and Testing the Geometry	141
6.5	Symmetries	141
6.5.1	Example - Collins or Figure Eight Quadrupole	142
6.5.2	Coil Geometry	143
6.5.3	Yoke Geometry	145
6.6	The Vector Potential Boundary Condition	146
6.6.1	Simple Dipole	147
6.6.2	The Simple Dipole with Vector Potential Boundary Conditions	147
6.6.3	The Vector Potential Boundary Condition for Optimizing the Quadrupole Pole	153
6.6.4	Other Applications of the Vector Potential Boundary Conditions	164
6.7	Chapter Closure	165
6.8	Problems	169
7	Stored Energy, Magnetic Forces and Dynamic Effects	171
7.1	Force on Coils	171
7.2	Force on a Pole	173
7.2.1	Units	173
7.2.2	A Reference Point	174
7.3	Magnet Stored Energy	174
7.3.1	Inductance	175
7.4	Eddy Currents	177
7.4.1	Field Attenuation due to Eddy Currents in a Semi-infinite Conductive Horizontal Plate	178
7.4.2	Field Attenuation due to Eddy Currents in a Pair of Semi-infinite Conductive Vertical Plates	182

7.4.3	Field Attenuation due to Eddy Currents in a Closed Rectangular Chamber	183
7.4.4	Field Amplification	184
7.5	Chapter Closure	191
7.6	Problems	192
8	Magnetic Measurements	195
8.1	The Vector Potential	196
8.1.1	Fourier Analysis	198
8.2	Output Voltage	200
8.3	The Compensated Coil	201
8.3.1	The Quadrupole Coil	203
8.3.2	The Dipole Coil	203
8.3.3	The Sextupole Coil	204
8.4	“Spilldown” and Magnetic Center	204
8.4.1	Quadrupole Magnetic Center	206
8.4.2	Sextupole Magnetic Center	207
8.5	Rotating Coil Magnetic Measurements	208
8.5.1	The Measurement System	209
8.6	Fourier Analysis	211
8.6.1	Uncompensated Signal	212
8.6.2	Compensated Signal	213
8.6.3	Expressions for the Integrated Multipole Fields	213
8.6.4	Excitation and Transfer Function	214
8.6.5	Relative Phases	215
8.6.6	Units	216
8.7	Measurements and Output	216
8.7.1	Measurement Plan	216
8.7.2	Raw Data Output	217
8.7.3	Bucking Ratio	217
8.7.4	Normalized Multipole Errors	218
8.7.5	Error Spectrum Normalized to the Required Good Field Radius	219
8.7.6	Magnetic Center	219
8.8	Measurement Output	220
8.8.1	Tabular Output	221
8.9	Analog Output (Iso-Error Plots)	221
8.10	Chapter Closure	224
8.11	Problems	225

9 Magnet Yoke Design and Fabrication	229
9.1 Introduction	229
9.2 Saturation	229
9.3 Two Dimensional Design	231
9.4 Three Dimensional Design	232
9.4.1 Dipole Fringe Field	232
9.4.2 Quadrupole Fringe Field	234
9.5 Solid Iron or Steel Laminations	238
9.5.1 Reproducibility and Symmetry	238
9.5.2 Solid Iron Cores	238
9.5.3 Laminated Steel Cores	239
9.5.4 Economics	240
9.5.5 Laminated Yoke Fabrication	241
9.6 Yoke Assembly/Fabrication Techniques	242
9.6.1 Gluing	244
9.6.2 Welded Laminated Yokes	251
9.6.3 Mechanically Assembled Laminated Yokes	253
9.7 Core Grounding	261
9.8 Chapter Closure	261
9.9 Chapter Appendix	264
10 Magnet Coil Fabrication	267
10.1 Introduction	267
10.1.1 Conductor Size and Turn to Turn Insulation	267
10.1.2 Coil Winding	268
10.1.3 Coil Potting (Encapsulation)	271
10.2 Coil Failures	278
10.2.1 Specifications	278
10.2.2 Measurements and Tests	279
10.3 Chapter Closure	284
11 Magnet Assembly	285
11.1 Introduction	285
11.2 Coil Supports and Bussing	285
11.2.1 Bussing	286
11.2.2 Magnet Tests	293
11.3 Chapter Closure	295
12 Magnet Installation and Alignment	297
12.1 Introduction	297
12.2 Magnet Support	298
12.2.1 Predetermined Alignment	298
12.2.2 Generic Fiducialization	299

12.2.3 Adjusted Alignment	300
12.2.4 Adjustable Struts	303
12.2.5 Adjustable Support Blocks	306
12.2.6 Pedigreed Fiducialization	308
12.3 Chapter Closure	310
Solutions	313
References	327
Index	329