

CONTENTS

Preface	xv
CHAPTER 1	
Introduction	1
CHAPTER 2	
Lagrangian Method	5
2.1 Introduction	6
2.2 Definition of Variable and Notation	7
2.3 The Governing Equation	13
2.4 Equation of State	15
2.5 Calculation Procedures and Finite Differences	15
2.6 Sliding Interface Treatments	24
References	30
CHAPTER 3	
Eulerian Method	31
3.1 Introduction	32
3.2 General Description of Physical Formulation	33
3.2.1 The Conservation Equation for a Stress-Supporting Medium	33
3.2.2 Equation of State	34
3.2.2.1 Stress in Elastic Regime	34
3.2.2.2 Stresses in Plastic Regime	35
3.2.2.3 Hydrostatic Pressure	36
3.2.2.4 Yield Criterion	36
3.2.2.5 Stress Correction for Rigid Body Rotation	37

3.2.3	Spall	38
3.2.3.1	Melting	38
3.2.3.2	Spall	39
3.2.3.3	Fracture	39
3.3	Computational Scheme	39
3.3.1	General Discussion	39
3.3.2	Summary of Calculation Procedure	40
3.3.2.1	Phase I: Lagrangian Phase	40
3.3.2.2	Phase II: Particle Transport and Remapping	41
3.3.3	Lagrangian Phase	41
3.3.3.1	Equations to be Solved in the Radial Direction	41
3.3.3.2	Lagrangian Phase Calculation	43
3.3.3.3	Summary of Equations in the Axial Direction	49
3.3.4	Stress Calculation in the Plastic Regime of Flow	51
3.3.4.1	Radial Direction	51
3.3.4.2	Axial Direction	54
3.3.5	Particle Transport and Remapping	55
3.3.5.1	Average Velocity for the Particle	55
3.3.5.2	Particle Treatment for Void or Multi-material Cell	55
3.3.6	Computation for Spall	58
3.3.6.1	When Spalled	58
3.3.6.2	Recombination	59
3.3.6.3	Propagation of Fracture Surface	59
3.3.7	Time Step Control	59
3.4	Truncation Error Analysis	61
3.4.1	Mass	61
3.4.2	Radial Momentum	63
3.4.3	Axial Momentum	66
3.4.4	Internal Energy	68
3.4.5	Deviatoric Stresses	69
3.5	Equivalent Plastic Strain	70
3.6	FCT Applied to Second-Order PIC	72
3.6.1	Introduction	72
3.6.2	Modified Mass Transport	72

3.6.3 The Modified FCT Analysis	76
References	78
CHAPTER 4	
Artificial Viscosity and Shock Calculations	81
4.1 Introduction	82
4.2 Basic Governing Equations	83
4.3 Artificial Viscosity in One-Dimensional Code	84
4.4 Artificial Viscosity in Two-Dimensional Code	86
4.5 With and Without Artificial Viscosity Methods	87
4.6 Sample Problem Calculations	89
4.7 Conclusions and Discussions	94
References	97
CHAPTER 5	
Numerical Simulations of Oblique	
Shock-Wave Reflection	99
5.1 Introduction	100
5.2 Eulerian Method	101
5.3 Lagrangian Method	103
5.4 Numerical Calculations and Results	105
5.4.1 Regular Reflection	107
5.4.2 Mach Reflection	112
5.5 Conclusions	114
References	115
CHAPTER 6	
Comparisons Between the Cell-Centered and Staggered	
Mesh Lagrangian Hydrodynamics	117
6.1 Introduction	118
6.2 A TVD Lagrangian Scheme	120
6.3 The DIVU Limiter	123
6.4 Vertex Velocity Definition	123
6.5 Staggered Mesh	125
6.6 The Mesa and Unicorn Method	126
6.7 Sample Results	128
6.8 Conclusions	132
References	135

CHAPTER 7

Multiphase Flow Treatment	137
7.1 Introduction	138
7.2 Two-phase Flow Model Equations	140
7.2.1 Basic Equation Set	140
7.2.2 Soo's Momentum Equations	142
7.2.3 Extended 'Rudinger-Chang' Momentum Equations	143
7.2.4 Hancox <i>et al.</i> Momentum Equations	144
7.2.5 Gidaspow's Momentum Equations	145
7.3 Characteristics for the Five Two-phase Flow Equation Sets	146
7.4 The Drag Function and Phase Change Rates	148
7.5 Numerical Solution Procedure	150
7.6 A More Stable Numerical Scheme	152
7.7 Description of Test Problems	153
7.7.1 Batch Settling of a Two-phase Mixture	154
7.7.2 One-dimensional Fluidized Bed	154
7.7.3 Simulation of Two-phase Jet Impinged on Vertical Plate	155
7.7.4 Results of Computations and Discussion	155
7.8 Conclusions	161
References	162

CHAPTER 8

Equation of State, Constitutive Relationship and High Explosive	165
8.1 Introduction to the Equation of State	165
8.2 The Mie–Grüneisen EOS and the Simple u_s , u_p Model	165
8.3 The Osborne Model	167
8.4 The Tillotson Equation of State	167
8.5 Introduction to the Constitutive Relationship	168
8.6 Quadratic Model	168
8.7 Steinberg-Guinan Model	169
8.8 Steinberg's New Model	171
8.9 High Explosive	174

8.9.1	Introduction	174
8.9.2	JWL Equation of State	175
8.9.3	Small Variation of JWL-EOS	177
	References	177
 CHAPTER 9		
	Shaped Charge Problems	179
9.1	Introduction	179
9.2	Shaped Charge Calculations by Lagrangian Method without Slip	179
9.3	Calculation of Shaped Charge Problem with Slip by Lagrangian Method	180
9.4	Shaped Charge Calculations using Eulerian Method	185
9.4.1	Viper Shaped Charge	185
9.4.2	Tantalum Hemi-spherical Shaped Charge	187
9.4.3	Bi-conical Copper Shaped Charge	190
9.4.4	Oil Well Perforator P-C	194
9.4.5	Copper Hemi-spherical Liner with PBX-W-113 (Energetic Explosive)	194
9.4.6	Calculations of the Hemi-spherical Copper Shaped Charge	194
9.4.7	Bi-conical Copper Shaped Charge with PBX-9404	204
9.4.8	Calculations of the BRL Precision Copper Shaped Charge	206
9.4.9	Shaped Charges of Tungsten-copper Alloy	208
	References	215
 CHAPTER 10		
	Explosive Formed Projectile	217
10.1	Introduction	217
10.2	Calculation of Explosive Formed Projectile with Combination of Lagrangian and Eulerian Codes	217
10.3	Copper EFP with Foam	218
10.4	Copper EFP without Foam	226
10.5	Non-axisymmetric Tantalum EFP Warhead	226

CHAPTER 11

The Penetration of Shaped Charge Jet	233
11.1 Introduction	233
11.2 Calculations of Tungsten Rod Penetrating Aluminum Target	233
11.3 Calculations of Copper Rod Penetrating Steel Plate	235
11.4 Tantalum Shaped Charge Penetrates into Steel Block	238
11.5 Tantalum Shaped Charge Penetrates into Steel Plate, Water, and Another Steel Plate	239
11.6 Copper-lead Shaped Charge Penetrates into Steel Block	240
11.7 Bi-conical Copper-lead Powder Shaped Charge Penetrates into Steel Block	246
11.8 Bi-conical Copper Shaped Charge Penetrates into Thin Steel Plate, Water, Thick Steel Plate and Rock	246
11.9 Viper Shaped Charge Penetrates into Steel Block	246
11.10 Computational Assessment of LEAP Performance with Different Lethality Enhancements	252
11.11 Lethality Assessments for Ascent-phase Interceptor Impacts on a Generic Chemical Submunition Target	256
References	267

CHAPTER 12

Oil Well Perforator Design Using 2D Eulerian Code	269
12.1 Introduction	270
12.2 Description of the 2D Eulerian Code	274
12.3 Equation of State and Constitutive Relation	277
12.4 Shaped Charge Jet Characteristics	278
12.5 Jet Formation and Penetration as Compared with Experimental Data	280
12.6 Perforators of 4.4 cm Charge Diameter	283
12.7 Perforators of 3.6 cm Charge Diameter	289
12.8 Discussions	294
12.9 Conclusions	298
References	299

APPENDIX A

One Dimensional Radiation Hydrodynamics	301
A.1 Introduction	302

A.2	Mathematical Theory of Radiation Hydrodynamics	303
A.2.1	Introduction	303
A.2.2	Radiation Transport Equation	305
A.2.3	Non-equilibrium Diffusion Equation with Compton Scattering	307
A.2.4	Non-equilibrium Diffusion Equations in an Inertial Frame	311
A.2.5	Conservation Laws	314
A.3	Numerical Analysis	316
A.3.1	Difference Equations	316
A.3.2	Boundary Conditions	324
A.3.3	Opacity Averaging Procedure	326
A.3.4	Variable Eddington Factor	330
A.3.5	Scattering Terms	338
A.3.6	Difference Equation for the Conservation of Momentum and Energy	345
A.4	Formulae for the First Moment of the Radiative Transfer Equation in 1D Geometry	347
A.5	Properties of an Implicit Difference Approximation to the Wave Equation	353
	References	356
 APPENDIX B		
	Thermonuclear Burn of Deuterium-Tritium Sphere	357
B.1	Introduction	358
B.2	The Governing Equations	359
B.3	The Thermonuclear Reaction Rate	362
B.4	Calculation Procedure	364
B.5	Radiation Transport Calculation	366
B.6	Some Important Fission Reactions	369
	References	370
 APPENDIX C		
	Hugoniot Data	371
	Author Index	375
	Subject Index	377