

Chapter 1

Introduction to Developed Turbulence

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This is a short course on developed turbulence, weak and strong. The main emphasis is on fundamental properties like universality and symmetries. Two main notions are explained: i) fluxes of dynamical integrals of motion, ii) statistical integrals of motion.

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1.1. Introduction

Turbulence is a state of a physical system with many interacting degrees of freedom deviated far from equilibrium. This state is irregular both in time and in space. Turbulence can be maintained by some external influence or it can be decaying turbulence on the way of relaxation to equilibrium. As the term suggests, it first appeared in fluid mechanics and was later generalized for far-from-equilibrium states in solids and plasma. For example, obstacle of size L placed into fluid moving with velocity V provides for a turbulent wake if the Reynolds number is large: $Re = VL/\nu \gg 1$. Here ν is the kinematic viscosity. At large Re , flow perturbations produced at the scale L have their viscous dissipation small compared to the nonlinear effects.

Nonlinearity produces motions of smaller and smaller scales until viscous dissipation stops this at a scale much smaller than L so that there is a wide (so-called inertial) interval of scales where viscosity is negligible and nonlinearity dominates. Another example is the system of waves excited on a fluid surface by wind or moving bodies and in plasma and solids by external electromagnetic fields. The state of such system is called wave turbulence when the wavelength of the waves excited strongly differs from the wavelength of the waves that effectively dissipate. Nonlinear interaction excites waves in the interval of wavelengths (called transparency window, or inertial interval) between the injection and dissipation scales.

The ensuing complicated and irregular dynamics calls for a statistical description based on averaging either over regions of space or intervals of time. Here we focus on a single-time statistics of steady turbulence that is on the spatial structure of fluctuations. Because of the conceptual simplicity of the inertial range, it is natural to ask if our expectation of universality—that is, freedom from the details of external forcing and internal friction—is true at the level of a physical law. Another facet of the universality problem concerns features that are common to different turbulent systems. This quest for universality is motivated by the hope of being able to distinguish general principles that govern far-from-equilibrium systems, similar in scope to the variational principles that govern thermal equilibrium.

Constraints on dynamics are imposed by conservation laws, and therefore conserved quantities must play an essential role in turbulence. The conservation laws are broken by pumping and dissipation, but both factors do not act in the inertial interval. For example, in the incompressible turbulence, the kinetic energy is pumped by external forcing and is dissipated by viscosity. According to the idea suggested by Richardson in 1921, the kinetic energy flows throughout the inertial interval of scales in a cascade-like process. The cascade idea explains the basic macroscopic manifestation of turbulence: the rate of dissipation of the dynamical integral of motion has a finite limit when the dissipation coefficient tends to zero. For example, the mean rate of the viscous energy dissipation does not depend on viscosity at large Reynolds numbers. That means that a symmetry of the inviscid equation (here, time-reversal invariance) is broken by the presence of the viscous term, even though the latter might have been expected to become negligible in the limit $Re \rightarrow \infty$.

The cascade idea fixes only the mean flux of the respective integral of motion demanding it to be constant across the inertial interval of scales. We shall see that flux constancy determines the system completely only for weakly nonlinear system (where the statistics is close to Gaussian). To describe an entire turbulence statistics of strongly interacting systems, one has to solve problems on a case-by-case basis with most cases still

unsolved. Particularly difficult (and interesting) are the cases with broken scale invariance where knowledge of flux does not allow one to predict even the order of magnitude of high moments. We describe the new concept of statistical integrals of motion which allows for the description of system with broken scale invariance.

1.2. Weak wave turbulence

From a theoretical point of view, the simplest case is the turbulence of weakly interacting waves. Examples include waves on the water surface, waves in plasma with and without magnetic field, spin waves in magnetics. We assume spatial homogeneity and denote $a_{\mathbf{k}}$ the amplitude of the wave with the wavevector \mathbf{k} . When the amplitude is small, it satisfies the linear equation

$$\partial a_{\mathbf{k}}/\partial t = -i\omega_{\mathbf{k}}a_{\mathbf{k}} + f_{\mathbf{k}}(t) - \gamma_{\mathbf{k}}a_{\mathbf{k}} . \quad (1.1)$$

Here the dispersion law $\omega_{\mathbf{k}}$ describes wave propagation, $\gamma_{\mathbf{k}}$ is the linear damping rate and $f_{\mathbf{k}}$ describes pumping. For the linear system, $a_{\mathbf{k}}$ is different from zero only in the regions of \mathbf{k} -space where $f_{\mathbf{k}}$ is nonzero. To describe wave turbulence which involves wavenumbers outside the pumping region, one must account for the interaction between different waves. Considering for a moment wave system as closed (that is, without external pumping and dissipation) one can describe it as a Hamiltonian system using wave amplitudes as normal canonical variables (see, for instance, the monograph¹). At small amplitudes, the Hamiltonian can be written as an expansion over $a_{\mathbf{k}}$, where the second-order term describes non-interacting waves and high-order terms determine the interaction:

$$H = \int \omega_{\mathbf{k}}|a_{\mathbf{k}}|^2 d\mathbf{k} \quad (1.2)$$

$$+ \int \left(V_{123}a_1a_2^*a_3^* + c.c. \right) \delta(\mathbf{k}_1 - \mathbf{k}_2 - \mathbf{k}_3) d\mathbf{k}_1 d\mathbf{k}_2 d\mathbf{k}_3 + O(a^4).$$

Here $V_{123} = V(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3)$ is the interaction vertex and c.c. means complex conjugation. In the Hamiltonian expansion, we presume every subsequent term smaller than the previous one, in particular, $\xi_{\mathbf{k}} = |V_{\mathbf{k}\mathbf{k}\mathbf{k}}a_{\mathbf{k}}|k^d/\omega_{\mathbf{k}} \ll 1$. Wave turbulence that satisfies this condition is called weak turbulence. Here d is the space dimensionality which can be 1, 2 or 3.

The dynamic equation which accounts for pumping, damping, wave propagation and interaction has thus the following form:

$$\partial a_{\mathbf{k}}/\partial t = -i\delta H/\delta a_{\mathbf{k}}^* + f_{\mathbf{k}}(t) - \gamma_{\mathbf{k}}a_{\mathbf{k}} . \quad (1.3)$$

It is likely that the statistics of the weak turbulence at $k \gg k_f$ is close to Gaussian for wide classes of pumping statistics (that has not been shown rigorously though). This is definitely the case for the random force with the statistics not very much different from Gaussian. We consider here and below a pumping by a Gaussian random force statistically isotropic and homogeneous in space, and white in time:

$$\langle f_k(t) f_{k'}^*(t') \rangle = F(k) \delta(\mathbf{k} + \mathbf{k}') \delta(t - t'). \quad (1.4)$$

Angular brackets mean spatial average. We assume $\gamma_k \ll \omega_k$ (for waves to be well defined) and that $F(k)$ is nonzero only around some k_f .

Since the dynamic equation (1.3) contains a quadratic nonlinearity then the statistical description in terms of moments encounters the closure problem: the time derivative of the second moment is expressed via the third one, the time derivative of the third moment is expressed via the fourth one etc. Fortunately, weak turbulence in the inertial interval is expected to have the statistics close to Gaussian so one can express the fourth moment as the product of two second ones. As a result one gets a closed equation for the single-time pair correlation function¹ $\langle a_k a_{k'} \rangle = n_k \delta(\mathbf{k} + \mathbf{k}')$

$$\begin{aligned} \frac{\partial n_k}{\partial t} &= F_k - \gamma_k n_k + I_k^{(3)}, \\ I_k^{(3)} &= \int (U_{k12} - U_{1k2} - U_{2k1}) d\mathbf{k}_1 d\mathbf{k}_2, \end{aligned} \quad (1.5)$$

$$U_{123} = \pi [n_2 n_3 - n_1 (n_2 + n_3)] |V_{123}|^2 \delta(\mathbf{k}_1 - \mathbf{k}_2 - \mathbf{k}_3) \delta(\omega_1 - \omega_2 - \omega_3).$$

It is called kinetic equation for waves. The collision integral $I_k^{(3)}$ results from the cubic terms in the Hamiltonian i.e. from the quadratic terms in the equations for amplitudes. It can be *interpreted* as describing three-wave interactions: the first term in the integral (1.5) corresponds to a decay of a given wave while the second and third ones correspond to a confluence with other wave.

One can estimate from (1.5) the inverse time of nonlinear interaction at a given k as $|V(k, k, k)|^2 n(k) k^d / \omega(k)$. We define k_d as the wavenumber where this inverse time is comparable to $\gamma(k)$ and assume that nonlinearity dominates over dissipation at $k \ll k_d$. As has been noted, wave turbulence appears when there is a wide (inertial) interval of scales where both pumping and damping are negligible, which requires $k_d \gg k_f$, the condition analogous to $Re \gg 1$. This is schematically shown in Fig. 1.

The presence of frequency delta-function in $I_k^{(3)}$ means that in the first order of perturbation theory in wave interaction we account only for resonant processes which conserve the quadratic part of the energy $E = \int \omega_k n_k d\mathbf{k} = \int E_k dk$. For the cascade picture to be valid, the collision integral has to converge in the inertial interval which means that

energy exchange is small between motions of vastly different scales, the property called interaction locality in k -space. Consider now a statistical steady state established under the action of pumping and dissipation. Let us multiply (1.5) by ω_k and integrate it over either interior or exterior of the ball with radius k . Taking $k_f \ll k \ll k_d$, one sees that the energy flux through any spherical surface (Ω is a solid angle), is constant in the inertial interval and is equal to the energy production/dissipation rate ϵ :

$$P_k = \int_0^k k^{d-1} dk \int d\Omega \omega_k I_k^{(3)} = \int \omega_k F_k d\mathbf{k} = \int \gamma_k E_k dk = \epsilon. \quad (1.6)$$

This (integral) equation determines n_k . Let us assume now that the

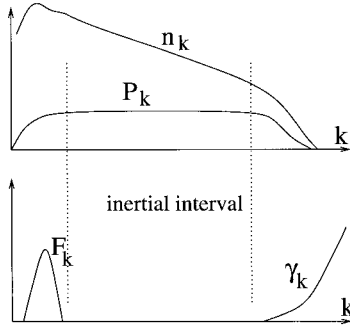


Fig. 1.1. A schematic picture of the cascade.

medium (characterized by the Hamiltonian coefficients) can be considered isotropic at the scales in the inertial interval. In addition, for scales much larger or much smaller than a typical scale (like Debye radius in plasma or the depth of the water) the medium is usually scale invariant: $\omega(k) = ck^\alpha$ and $|V(\mathbf{k}, \mathbf{k}_1, \mathbf{k}_2)|^2 = V_0^2 k^{2m} \chi(\mathbf{k}_1/k, \mathbf{k}_2/k)$ with $\chi \simeq 1$. Remind that we presumed statistically isotropic force. In this case, the pair correlation function that describes a steady cascade is also isotropic and scale invariant:

$$n_k \simeq \epsilon^{1/2} V_0^{-1} k^{-m-d}. \quad (1.7)$$

One can show that (1.7), called Zakharov spectrum, turns $I_k^{(3)}$ into zero.¹

If the dispersion relation $\omega(k)$ does not allow for the resonance condition $\omega(k_1) + \omega(k_2) = \omega(|\mathbf{k}_1 + \mathbf{k}_2|)$ then the three-wave collision integral is zero and one has to account for four-wave scattering which is always resonant. In other words, whatever the $\omega(k)$ relationship is, one can always find four wavevectors that satisfy $\omega(k_1) + \omega(k_2) = \omega(k_3) + \omega(k_4)$ and $\mathbf{k}_1 + \mathbf{k}_2 = \mathbf{k}_3 + \mathbf{k}_4$.

The collision integral that describes scattering,

$$I_k^{(4)} = \frac{\pi}{2} \int |T_{k123}|^2 [n_2 n_3 (n_1 + n_k) - n_1 n_k (n_2 + n_3)] \delta(\mathbf{k} + \mathbf{k}_1 - \mathbf{k}_2 - \mathbf{k}_3) \times \delta(\omega_k + \omega_1 - \omega_2 - \omega_3) d\mathbf{k}_1 d\mathbf{k}_2 d\mathbf{k}_3, \quad (1.8)$$

conserves the energy and the wave action $N = \int n_k d\mathbf{k}$ (the number of waves). Pumping generally provides for an input of both E and N . If there are two inertial intervals (at $k \gg k_f$ and $k \ll k_f$), then there should be two cascades. Indeed, if $\omega(k)$ grows with k , then the absorption of a finite amount of E at $k_d \rightarrow \infty$ corresponds to an absorption of an infinitely small N . It is thus clear that the flux of N has to go in the opposite direction, that is, to large scales. A so-called inverse cascade with the constant flux of N can thus be realized at $k \ll k_f$. A sink at small k can be provided by a wall friction in the container or by long waves leaving the turbulent region in open spaces (like in sea storms). The collision integral $I_k^{(3)}$ involves products of two n_k , so that the flux constancy requires $E_k \propto \epsilon^{1/2}$, while for the four-wave case $I_k^{(4)} \propto n^3$ gives $E_k \propto \epsilon^{1/3}$. In many cases (when there is a complete self-similarity) this knowledge is sufficient to obtain the scaling of E_k from a dimensional reasoning without actually calculating V and T . For example, short waves on a deep water are characterized by the surface tension σ and density ρ , so the dispersion relation must be $\omega_k \sim \sqrt{\sigma k^3 / \rho}$, which allows for the three-wave resonance, and thus $E_k \sim \epsilon^{1/2} (\rho \sigma)^{1/4} k^{-7/4}$. For long waves on a deep water, the surface-restoring force is dominated by gravity so that the gravity acceleration g replaces σ as a defining parameter and $\omega_k \sim \sqrt{gk}$. Such dispersion law does not allow for the three-wave resonance so that the dominant interaction is four-wave scattering which permits two cascades. The direct energy cascade corresponds to $E_k \sim \epsilon^{1/3} \rho^{2/3} g^{1/2} k^{-5/2}$. The inverse cascade carries the flux of N which we denote Q , it has the dimensionality $[Q] = [e]/[\omega_k]$ and corresponds to $E_k \sim Q^{1/3} \rho^{2/3} g^{2/3} k^{-7/3}$.

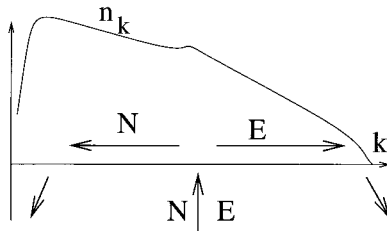


Fig. 1.2. Two cascades under four-wave interaction.

Since the statistics of weak turbulence is near Gaussian, it is completely

determined by the pair correlation function, which is in turn determined by the respective flux. We thus conclude that weak turbulence is universal in the inertial interval.

1.3. Strong wave turbulence

One cannot treat wave turbulence as a set of weakly interacting waves when the wave amplitudes are big enough (so that $\xi_k \geq 1$) and also in a particular case of linear (acoustic) dispersion relation $\omega(k) = ck$ for arbitrarily small amplitudes. Indeed, there is no dispersion of wave velocity for acoustic waves so that waves moving in the same direction interact strongly and produce shock waves when viscosity is small. Formally, there is a singularity due to coinciding arguments of delta-functions in (1.5) (and in the higher terms of perturbation expansion for $\partial n_k/\partial t$), which is thus invalid at however small amplitudes. Still, some features of the statistics of acoustic turbulence can be understood even without closed description. We discuss this in a one-dimensional case which pertains, for instance, to sound propagating in long pipes. Since weak shocks are stable with respect to transverse perturbations,² quasi one-dimensional perturbations may propagate in 2D and 3D as well. In the frame of reference moving with the sound velocity, the weakly compressible 1d flows ($u \ll c$) are described by the Burgers equation^{2,3}

$$u_t + uu_x - \nu u_{xx} = 0. \quad (1.9)$$

Burgers equation has a propagating shock-wave solution $u = 2v\{1 + \exp[v(x - vt)/\nu]\}^{-1}$ with the energy dissipation rate $\nu \int u_x^2 dx$ independent of ν . The shock width ν/v is a dissipative scale and we shall consider acoustic turbulence produced by a pumping correlated on much larger scales (for example, pumping a pipe from one end by frequencies much less than cv/ν). After some time, it will develop shocks at random positions. Here we consider the single-time statistics of the Galilean invariant velocity difference $\delta u(x, t) = u(x, t) - u(0, t)$. The moments of δu are called *structure functions* $S_n(x, t) = \langle [u(x, t) - u(0, t)]^n \rangle$. Quadratic nonlinearity makes the time derivative of the second moment to be expressed via the third one:

$$\frac{\partial S_2}{\partial t} = -\frac{\partial S_3}{3\partial x} - 4\epsilon + \nu \frac{\partial^2 S_2}{\partial x^2}. \quad (1.10)$$

Here $\epsilon = \nu \langle u_x^2 \rangle$ is the mean energy dissipation rate. Equation (1.10) describes both a free decay (then ϵ depends on t) and the case of a permanently acting pumping which generates turbulence statistically steady at scales less than the pumping length. In the first case, $\partial S_2/\partial t \simeq S_2 u/L \ll \epsilon \simeq u^3/L$

(where L is a typical distance between shocks) while in the second case $\partial S_2/\partial t = 0$ so that $S_3 = 12\epsilon x + \nu\partial S_2/\partial x$.

Consider now a limit $\nu \rightarrow 0$ at fixed x (and t for decaying turbulence). Shock dissipation provides for a finite limit of ϵ at $\nu \rightarrow 0$, then

$$S_3 = -12\epsilon x. \quad (1.11)$$

This formula is a direct analog of (1.6). Indeed, the Fourier transform of (1.10) describes the energy density $E_k = \langle |u_k|^2 \rangle / 2$ which satisfies the equation $(\partial_t - \nu k^2)E_k = -\partial P_k/\partial k$ where the k -space flux is

$$P_k = \int_0^k dk' \int_{-\infty}^{\infty} dx S_3(x) k' \sin(k'x) / 24.$$

It is thus the flux constancy that fixes $S_3(x)$ which is universal, i.e., it is determined solely by ϵ and depends neither on the initial statistics of decay nor on the pumping for steady turbulence. On the contrary, other structure functions $S_n(x)$ are not given by $(\epsilon x)^{n/3}$. Indeed, the scaling of the structure functions can be readily understood for any dilute set of shocks (when shocks do not cluster in space) which seems to be the case both for smooth initial conditions and a large-scale pumping in Burgers turbulence. In this case, $S_n(x) \sim C_n |x|^n + C'_n |x|$, where the first term comes from the regular (smooth) parts of the velocity (the right x -interval in Fig. 1.3.), while the second term comes from $O(x)$ probability to have a shock in the interval x . The scaling exponents, $\xi_n = d \ln S_n / d \ln x$, thus behave as follows: $\xi_n = n$ for $n \leq 1$ and $\xi_n = 1$ for $n > 1$. That means that the probability density function (PDF) of the velocity difference in the inertial interval $P(\delta u, x)$ is not scale-invariant, i.e., the function of the re-scaled velocity difference $\delta u/x^a$ cannot be made scale-independent for any a . As one goes to smaller scales, the low-order moments decrease faster than the high-order ones, that means that the smaller the scale, the more probable are large fluctuations. In other words, the level of fluctuations increases with the resolution. When the scaling exponents ξ_n do not lie on a straight line, this is called an anomalous scaling since it is related again to the symmetry (scale invariance) of the PDF broken by pumping and not restored even when $x/L \rightarrow 0$. As an alternative to the description in terms of structures (shocks), one can relate the anomalous scaling in Burgers turbulence to additional integrals of motion. Indeed, the integrals $E_n = \int u^{2n} dx / 2$ are all conserved by the inviscid Burgers equation. Any shock dissipates the finite amount of E_n in the limit of $\nu \rightarrow 0$, so that similarly to (1.11), one denotes $\langle \dot{E}_n \rangle = \epsilon_n$ and obtains $S_{2n+1} = -4(2n+1)\epsilon_n x / (2n-1)$ for integer n .

Note that $S_2(x) \propto |x|$ corresponds to $E(k) \propto k^{-2}$, since every shock gives $u_k \propto 1/k$ at $k \ll v/\nu$, such that the energy spectrum is determined by

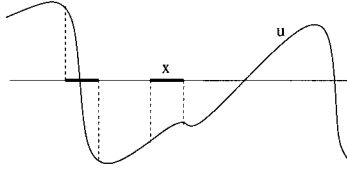


Fig. 1.3. Typical velocity profile in Burgers turbulence

the type of structures (shocks) rather than by energy flux constancy. Similar ideas were suggested for other types of strong wave turbulence assuming them to be dominated by different structures. Weak wave turbulence, being a set of weakly interacting plane waves, can be studied uniformly for different systems.¹ On the contrary, when the nonlinearity is strong, different structures appear. Broadly, one distinguishes conservative structures (like solitons and vortices) from dissipative structures which usually appear as a result of finite-time singularity of the non-dissipative equations (like shocks, light self-focussing, or wave collapse). For example, nonlinear wave packets are described by nonlinear Schrödinger equation,

$$i\Psi_t + \nabla^2\Psi + T|\Psi|^2\Psi = 0 . \quad (1.12)$$

Weak wave turbulence is determined by $|T|^2$ and is the same both for $T < 0$ (wave repulsion) and $T > 0$ (wave attraction). At high levels of nonlinearity, different signs of T correspond to dramatically different physics: at $T < 0$ one has a stable condensate, solitons and vortices, while at $T > 0$ instabilities dominate and wave collapse is possible at $d = 2, 3$. No analytic theory is yet available for strong turbulence described by (8.1).

Since the parameter of nonlinearity $\xi(k)$ generally depends on k , then there may exist weakly turbulent cascade up to some k_* , such that $\xi(k_*) \sim 1$ and strong turbulence beyond this wavenumber. In this case weak and strong turbulence can coexist in the same system. Presuming that some mechanism (for instance, wave breaking) prevents the development of wave amplitudes corresponding to $\xi_k \gg 1$, one may hypothesize that some cases of strong turbulence correspond to the balance between dispersion and nonlinearity local in k -space so that $\xi(k) = \text{const}$ throughout its domain in k -space. That would correspond to the spectrum $E_k \sim \omega_k^3 k^{-d} / |V_{kkk}|^2$ which is ultimately universal, or independent even of the flux (only the boundary k_* depends on the flux). For gravity waves, this gives $E_k = \rho g k^{-3}$, the same spectrum one obtains presuming wave profile to have cusps (another type of dissipative structure leading to whitecaps in stormy sea⁴). It is unclear if such flux-independent spectra are realized.

1.4. Incompressible turbulence

Incompressible fluid flow is described by the Navier-Stokes equation

$$\partial_t \mathbf{v}(\mathbf{r}, t) + \mathbf{v}(\mathbf{r}, t) \cdot \nabla \mathbf{v}(\mathbf{r}, t) - \nu \nabla^2 \mathbf{v}(\mathbf{r}, t) = -\nabla p(\mathbf{r}, t), \quad \text{div } \mathbf{v} = 0. \quad (1.13)$$

We are again interested in the structure functions $S_n(\mathbf{r}, t) = \langle [(\mathbf{v}(\mathbf{r}, t) - \mathbf{v}(0, t)) \cdot \mathbf{r}/r]^n \rangle$ and consider distance r smaller than the force correlation scale for a steady case and smaller than the size of turbulent region for a decay case. We treat first the three-dimensional case. Similar to (1.10), one can derive² the Karman-Howarth relation between S_2 and S_3 :

$$\frac{\partial S_2}{\partial t} = -\frac{1}{3r^4} \frac{\partial}{\partial r} (r^4 S_3) + \frac{4\epsilon}{3} + \frac{2\nu}{r^4} \frac{\partial}{\partial r} \left(r^4 \frac{\partial S_2}{\partial r} \right). \quad (1.14)$$

Here $\epsilon = \nu \langle (\nabla \mathbf{v})^2 \rangle$ is the mean energy dissipation rate. Neglecting time derivative (which is zero in a steady state and small comparing to ϵ for decaying turbulence) one can multiply (1.14) by r^4 and integrate: $S_3(r) = -4\epsilon r/5 + 6\nu dS_2(r)/dr$. Kolmogorov considered the limit $\nu \rightarrow 0$ for fixed r and *assumed* nonzero limit for ϵ which gives the so-called 4/5 law^{2,5,6}:

$$S_3 = -\frac{4}{5} \epsilon r. \quad (1.15)$$

This relation is a direct analog of (1.6) and (1.11). It also means that the kinetic energy has a constant flux in the inertial interval of scales (the viscous scale η is defined by $\nu S_2(\eta) \simeq \epsilon \eta^2$). On the first sight, it might appear from (1.13) that the dissipation rate of turbulent energy would vanish as $\nu \rightarrow 0$ (or as $Re \rightarrow \infty$), but an important feature of turbulence is that the average rate of the energy dissipation per unit mass, $\langle \epsilon \rangle$, remains finite in this limit: no matter how small the viscosity, or how high the Reynolds number, or how extensive the scale-range participating in the energy cascade, the energy flux remains equal to that injected at the stirring scale. Historically, this is the first example of what is now called ‘‘anomaly’’ in theoretical physics: a symmetry of the equation (here, time-reversal invariance) remains broken even as the symmetry-breaking factor (viscosity) becomes vanishingly small.⁷ If one screens a movie of steady turbulence backwards, we can tell that something is indeed wrong!

The law (1.15) implies that the third-order moment is universal, i.e. it does not depend on the details of the turbulence production but is determined solely by the mean energy dissipation rate. The rest of the structure functions have never been derived. Kolmogorov⁶ (and also Heisenberg, von Weizsacker and Onsager) presumed the pair correlation function to be determined only by ϵ and r which would give $S_2(r) \sim (\epsilon r)^{2/3}$ and the energy spectrum $E_k \sim \epsilon^{2/3} k^{-5/3}$. Experiments suggest that $\zeta_n = d \ln S_n / d \ln r$ lie on a smooth concave curve sketched in Fig. 1.4. . While ζ_2 is close to

$2/3$ it has to be a bit larger because experiments show that the slope at zero $d\zeta_n/dn$ is larger than $1/3$ while $\zeta(3) = 1$ in agreement with (1.15). Like in Burgers, the PDF of velocity differences in the inertial interval is not scale invariant in the 3D incompressible turbulence. So far, nobody was able to find an explicit relation between the anomalous scaling for 3D Navier-Stokes turbulence and either structures or additional integrals of motion.

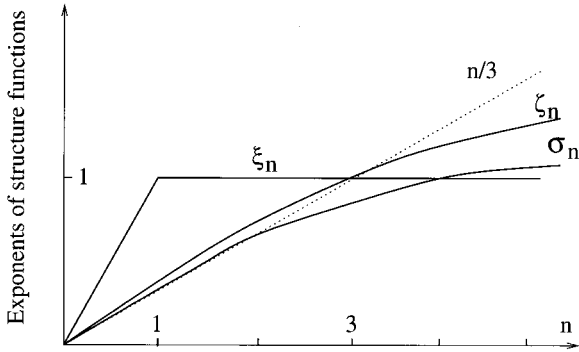


Fig. 1.4. The scaling exponents of the structure functions ξ_n for Burgers, ζ_n for 3D Navier-Stokes and σ_n for the passive scalar. The dotted straight line is $n/3$.

While not exact, Kolomogorov's approximation $S_2(\eta) \simeq (\epsilon\eta)^{2/3}$ can be used to estimate the viscous scale: $\eta \simeq LRe^{-3/4}$. The number of degrees of freedom involved into 3D incompressible turbulence can thus be roughly estimated as $N \sim (L/\eta)^3 \sim Re^{9/4}$. That means, in particular, that detailed computer simulations of water or oil pipe flows ($Re \sim 10^4 \div 10^7$) or turbulent cloud ($Re \sim 10^6 \div 10^9$) are out of question for a foreseeable future. To calculate correctly at least the large-scale part of the flow, it is desirable to have some theoretical model to parameterize the small-scale motions. The main obstacle here is the lack of qualitative understanding and quantitative description of how turbulence statistics changes with the scale. This breakdown of the scale invariance in the inertial range is another example of anomaly (effect of pumping scale does not disappear even at the limit $r/L \rightarrow 0$). Such an anomalous (or multifractal) scaling, is arguably an important feature of turbulence, which sets it apart from the usual critical phenomena: one needs to work out the behavior of moments of each order independently without succumbing to dimensional analysis. Anomalous scaling in turbulence is such that $\zeta_{2n} < n\zeta_2$ so that S_{2n}/S_2^n for $n > 2$ increases as $r \rightarrow 0$. The relative growth of high moments means that strong fluctuations become more probable as the scales become smaller. Its

practical importance is that it limits our ability to produce realistic models for small-scale turbulence.

2D Turbulence. Large-scale motions in shallow fluid can be approximately considered two-dimensional. When the velocities of such motions are much smaller than the velocities of the surface waves and the velocity of sound, such flows can be considered incompressible. Their description is important for understanding atmospheric and oceanic turbulence at the scales larger than the atmosphere height and the ocean depth. Vorticity $\omega = \text{curl } \mathbf{v} (= \nabla \times v)$ is a scalar in a two-dimensional flow. It is advected by the velocity field and dissipated by viscosity. Taking *curl* of the Navier-Stokes equation one gets

$$d\omega/dt = \partial_t \omega + (\mathbf{v} \cdot \nabla)\omega = \nu \nabla^2 \omega . \quad (1.16)$$

Two-dimensional incompressible inviscid flow just transports vorticity from place to place and thus conserves spatial averages of any function of vorticity, $\Omega_n \equiv \int \omega^n dr$. In particular, we now have the second quadratic inviscid invariant (in addition to energy) which is called *enstrophy*: $\Omega_2 = \int \omega^2 dr$. Since the spectral density of the energy is $|\mathbf{v}_k|^2/2$, while that of the enstrophy is $|\mathbf{k} \times \mathbf{v}_k|^2$, then (similarly to the cascades of E and N in wave turbulence under four-wave interaction) one expects that the direct cascade (towards large k) is that of enstrophy, while the inverse cascade is that of energy, as was suggested by Kraichnan.⁸ What about other Ω_n ? The intuition developed so far might suggest that the infinity of dynamical conservation laws must bring about anomalous scaling. Turbulence never fails to defy natural expectations as we shall see. Again, for the inverse energy cascade, there is no consistent theory except for the flux relation that can be derived similarly to (1.15):

$$S_3(r) = 4\epsilon r/3 . \quad (1.17)$$

The inverse cascade is observed in the atmosphere (at the scales $30 \div 500$ km) and in the laboratory experiments.⁹ Experimental data suggest that there is no anomalous scaling that is $S_n \propto r^{n/3}$. In particular, $S_2 \propto r^{2/3}$ which corresponds to $E_k \propto k^{-5/3}$. It is ironic that probably the most widely known statement on turbulence, the 5/3 spectrum suggested by Kolmogorov for 3D, is not correct in this case (even though the true scaling is close) while it is probably exact in the Kraichnan's inverse 2D cascade. Qualitatively, it is likely that the absence of anomalous scaling in the inverse cascade is associated with the growth of the typical turnover time (estimated, say, as $r/\sqrt{S_2}$) with the scale. As the inverse cascade proceeds, the fluctuations have enough time to get smoothed out, opposite to the direct cascade in 3D, where the turnover time decreases in the direction of the cascade.

Passive Scalar Turbulence. Before discussing the direct (enstrophy) cascade, we describe a similar, yet somewhat simpler problem of passive scalar turbulence which allows one to introduce the necessary notions of Lagrangian description of the fluid flow. Consider a scalar quantity $\theta(\mathbf{r}, t)$, which is subject to molecular diffusion and advection by the fluid flow, but has no back influence on the velocity (i.e. passive):

$$\partial_t \theta + (\mathbf{v} \cdot \nabla) \theta = \kappa \nabla^2 \theta + \varphi. \quad (1.18)$$

Here κ is molecular diffusivity. The examples of passive scalar are smoke in the air, salinity in the water and temperature when one can neglect thermal convection. Without pumping, dissipation and diffusion, ω and θ are advected in the same way in the same 2D flow: they are both Lagrangian invariants satisfying $d\omega/dt = d\theta/dt = 0$. However, note that vorticity is related to velocity, while the passive scalar is not. If the source φ produces fluctuations of θ on some scale L , then the inhomogeneous velocity field stretches, contracts and folds the field θ producing progressively smaller and smaller scales: this is the mechanism of the scalar cascade. If the rms velocity gradient is Λ , then molecular diffusion is substantial at the scales less than the diffusion scale $r_d = \sqrt{\kappa/\Lambda}$. For scalar turbulence, the ratio $Pe = L/r_d$, called Peclet number, plays the role of the Reynolds number. When $Pe \gg 1$, there is an inertial interval with a constant flux of θ^2 :

$$\langle (\mathbf{v}_1 \cdot \nabla_1 + \mathbf{v}_2 \cdot \nabla_2) \theta_1 \theta_2 \rangle = 2P, \quad (1.19)$$

where $P = \kappa \langle (\nabla \theta)^2 \rangle$ and subscripts denote the spatial points. In considering the passive scalar problem, the velocity statistics is presumed to be given. Still, the correlation function (1.19) mixes \mathbf{v} and θ and does not generally allow one to make a statement on any correlation function of θ . The proper way to describe the correlation functions of the scalar at the scales much larger than the diffusion scale is to employ the Lagrangian description that is to follow fluid trajectories.¹⁰ Indeed, if we neglect diffusion, then the equation (1.18) can be solved along the characteristics $\mathbf{R}(t)$ which are called Lagrangian trajectories and satisfy $d\mathbf{R}/dt = \mathbf{v}(\mathbf{R}, t)$. Presuming zero initial conditions for θ at $t \rightarrow -\infty$ we write

$$\theta(\mathbf{R}(t), t) = \int_{-\infty}^t \varphi(\mathbf{R}(t'), t') dt'. \quad (1.20)$$

In that way, the correlation functions of the scalar $F_n = \langle \theta(\mathbf{r}_1, t) \dots \theta(\mathbf{r}_n, t) \rangle$ can be obtained by integrating the correlation functions of the pumping along the trajectories that satisfy the final conditions $\mathbf{R}_i(t) = \mathbf{r}_i$. We consider a pumping which is Gaussian, statistically homogeneous and isotropic in space and white in time:

$$\langle \varphi(\mathbf{r}_1, t_1) \varphi(\mathbf{r}_2, t_2) \rangle = \Phi(|\mathbf{r}_1 - \mathbf{r}_2|) \delta(t_1 - t_2),$$

where the function Φ is constant at $r \ll L$ and goes to zero at $r \gg L$. The pumping provides for symmetry $\theta \rightarrow -\theta$ which makes only even correlation functions F_{2n} nonzero. The pair correlation function is as follows:

$$F_2(r, t) = \int_{-\infty}^t \Phi(R_{12}(t')) dt' . \quad (1.21)$$

Here $R_{12}(t') = |\mathbf{R}_1(t') - \mathbf{R}_2(t')|$ is the distance between two trajectories and $R_{12}(t) = r$. The function Φ essentially restricts the integration to the time interval when the distance $R_{12}(t') \leq L$. Simply speaking, the stationary pair correlation function of a tracer is $\Phi(0)$ (which is twice the injection rate of θ^2) times the average time $T_2(r, L)$ that two fluid particles spent within the correlation scale of the pumping. The larger r , the less time it takes for the particles to separate from r to L , and the less is $F_2(r)$. Of course, $T_{12}(r, L)$ depends on the properties of the velocity field. A general theory is available only when the velocity field is spatially smooth at the scale of the scalar pumping L . This so-called Batchelor regime happens, in particular, when the scalar cascade occurs at the scales less than the viscous scale of fluid turbulence.¹⁰⁻¹² This requires the Schmidt number ν/κ (called Prandtl number when θ is temperature) to be large, which is the case for very viscous liquids. In this case, one can approximate the velocity difference $\mathbf{v}(\mathbf{R}_1, t) - \mathbf{v}(\mathbf{R}_2, t) \approx \hat{\sigma}(t)\mathbf{R}_{12}(t)$ by the Lagrangian strain matrix $\sigma_{ij}(t) = \nabla_j v_i$. In this regime, the distance obeys the linear differential equation

$$\dot{\mathbf{R}}_{12}(t) = \hat{\sigma}(t)\mathbf{R}_{12}(t) . \quad (1.22)$$

The theory of such equations is well-developed and is related to what is called Lagrangian chaos since fluid trajectories separate exponentially as typical for systems with dynamical chaos (see, e.g.^{10,13}): at t much larger than the correlation time of the random process $\hat{\sigma}(t)$, all moments of R_{12} grow exponentially with time and $\langle \ln[R_{12}(t)/R_{12}(0)] \rangle = \lambda t$, where λ is called a senior Lyapunov exponent of the flow (note, that for the description of the scalar we need the flow taken backwards in time which is different from that taken forward because turbulence is irreversible). Dimensionally, $\lambda = \Lambda f(Re)$, where the limit of the function f at $Re \rightarrow \infty$ is unknown. We thus obtain:

$$F_2(r) = \Phi(0)\lambda^{-1} \ln(L/r) = 2P\lambda^{-1} \ln(L/r) . \quad (1.23)$$

In a similar way, one shows that for $n \ll \ln(L/r)$ all F_n are expressed via F_2 and the structure functions $S_{2n} = \langle [\theta(\mathbf{r}, t) - \theta(0, t)]^{2n} \rangle \simeq (P/\lambda)^n \ln^n(r/r_d)$ for $n \ll \ln(r/r_d)$. This can be generalized for an arbitrary statistics of pumping as long as it is finite-correlated in time.¹⁰

2D Enstrophy cascade. Now, one can use the analogy between passive scalar and vorticity in 2D.^{8,14} For the enstrophy cascade, one derives the flux relation analogous to (1.19):

$$\langle (\mathbf{v}_1 \cdot \nabla_1 + \mathbf{v}_2 \cdot \nabla_2) \omega_1 \omega_2 \rangle = 2D, \quad (1.24)$$

where $D = \langle \nu (\nabla \omega)^2 \rangle$. The flux relation along with $\omega = \text{curl } \mathbf{v}$ suggests the scaling $\delta v(r) \propto r$, so that velocity is close to spatially smooth (of course, it cannot be perfectly smooth to provide for a nonzero vorticity dissipation in the inviscid limit, but the possible singularities are indeed no stronger than logarithmic). This makes the vorticity cascade similar to the Batchelor regime of the passive scalar cascade with a notable change in that the rate of stretching λ acting on a given scale is not a constant but is logarithmically growing when the scale decreases. Since λ scales as vorticity, the law of renormalization can be established from dimensional reasoning and one gets $\langle \omega(\mathbf{r}, t) \omega(0, t) \rangle \sim [D \ln(L/r)]^{2/3}$ which corresponds to the energy spectrum $E_k \propto D^{2/3} k^{-3} \ln^{-1/3}(kL)$. High-order correlation functions of vorticity are also logarithmic, for instance, $\langle \omega^n(\mathbf{r}, t) \omega^n(0, t) \rangle \sim [D \ln(L/r)]^{2n/3}$. Note that both passive scalar in the Batchelor regime and vorticity cascade in 2D are universal, which is determined by the single flux (P and D respectively) despite the existence of the high-order conserved quantities. Experimental data and numerical simulations support these conclusions.^{9,10}

1.5. Zero modes and anomalous scaling

Let us now return to the Lagrangian description and discuss it when velocity is not spatially smooth, for example, that of the energy cascades in the inertial interval. One can assume that it is Lagrangian statistics which is determined by the energy flux when the distances between fluid trajectories are in the inertial interval. That assumption leads, in particular, to the Richardson law for the asymptotic growth of the interparticle distance:

$$\langle R_{12}^2(t) \rangle \sim \epsilon t^3, \quad (1.25)$$

first established from atmospheric observations (in 1926) and later confirmed experimentally for energy cascades both in 3D and in 2D. There is no consistent theoretical derivation of (1.25) and it is unclear whether it is exact (likely to be in 2D) or just approximate (possible in 3D). Semi-heuristic argument usually presented in textbooks is based on the mean-field estimate: $\dot{\mathbf{R}}_{12} = \delta \mathbf{v}(\mathbf{R}_{12}, t) \sim (\epsilon R_{12})^{1/3}$ which upon integration gives: $R_{12}^{2/3}(t) - R_{12}^{2/3}(0) \sim \epsilon^{1/3} t$. For the passive scalar it gives, by virtue of (1.21), $F_2(r) \sim \Phi(0) \epsilon^{-1/3} [L^{2/3} - r^{2/3}]$ as suggested by Oboukhov and Corrsin.^{15,16} The structure function is then $S_2(r) \sim \Phi(0) \epsilon^{-1/3} r^{2/3}$. Experiments measuring the scaling exponents $\sigma_n = d \ln S_n(r) / d \ln r$ generally give σ_2 close

to $2/3$ but higher exponents deviate from the straight line even stronger than the exponents of the velocity in 3D. Moreover, the scalar exponents σ_n are anomalous even when advecting velocity has a normal scaling like in 2D energy cascade.

To describe multi-point correlation functions or high-order structure functions one needs to study multi-particle statistics. Here an important question is what memory of the initial configuration remains when final distances far exceed initial ones. To answer this question one must analyze the conservation laws of turbulent diffusion. We now describe a general concept of conservation laws which, while conserved only on the average, still determine the statistical properties of strongly fluctuating systems. In a random system, it is always possible to find some fluctuating quantities whose ensemble averages do not change. We now ask a more subtle question: is it possible to find quantities that are expected to change on the dimensional grounds but they stay constant.^{7,10} Let us characterize n fluid particles in a random flow by inter-particle distances R_{ij} (between particles i and j) as in Figure 1.5. Consider homogeneous functions f of inter-particle distances with a nonzero degree ζ , i.e. $f(\lambda R_{ij}) = \lambda^\zeta f(R_{ij})$. When all the distances grow on average, say according to $\langle R_{ij}^2 \rangle \propto t^\alpha$, then one expects that a generic function grows as $f \propto t^{\alpha\zeta/2}$. How to build (specific) functions that are conserved on average, and which ζ -s they have? As the particles move in a random flow, the n -particle cloud grows in size while fluctuations in the shape of the cloud decrease in magnitude. Therefore, one may look for suitable functions of size and shape that are conserved because the growth of distances is compensated by the decrease of shape fluctuations.

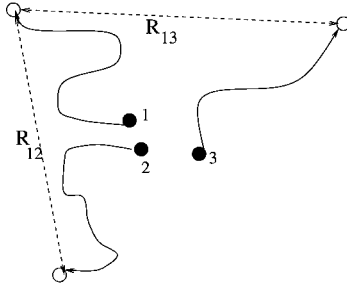


Fig. 1.5. Three fluid particles in a flow

For the simplest case of Brownian random walk, inter-particle distances grow by the diffusion law: $\langle R_{ij}^2(t) \rangle = R_{ij}^2(0) + \kappa t$, $\langle R_{ij}^4(t) \rangle = R_{ij}^4(0) + 2(d + 2)[R_{ij}^2(0)\kappa t + \kappa^2 t^2]/d$, etc. Here d is the space dimensionality. Two particles are characterized by a single distance. Any positive power of this distance

grows on the average. For three particles, one can build conserved quantities by taking the differences where all powers of t cancel out: $f_2 = \langle R_{12}^2 - R_{13}^2 \rangle$, $f_4 = \langle 2(d+2)R_{12}^2 R_{13}^2 - d(R_{12}^4 + R_{13}^4) \rangle$, etc. These polynomials are called harmonics since they are zero modes of the Laplacian in the 2-dimensional space of $\mathbf{R}_{12}, \mathbf{R}_{13}$. One can write the Laplacian as $\Delta = R^{1-2d} \partial_R R^{2d-1} \partial_R + \Delta_\theta$, where $R^2 = R_{12}^2 + R_{13}^2$ and Δ_θ is the angular Laplacian on $2d-1$ -dimensional unit sphere. Introducing the angle, $\theta = \arcsin(R_{12}/R)$, which characterizes the shape of the triangle, we see that the conservation of both $f_2 = \langle R^2 \cos 2\theta \rangle$ and $f_4 = \langle R^4 [(d+1) \cos^2 2\theta - 1] \rangle$ can be also described as due to cancellation between the growth of the radial part (as powers of t) and the decay of the angular part (as inverse powers of t). For n particles, the polynomial that involves all distances is proportional to R^{2n} (i.e. $\zeta_n = n$) and the respective shape fluctuations decay as t^{-n} .

The scaling exponents of the zero modes are thus determined by the laws that govern decrease of shape fluctuations. The zero modes, which are conserved statistically, exist for turbulent macroscopic diffusion as well. However, there is a major difference since the velocities of different particles are correlated in turbulence. Those mutual correlations make shape fluctuations decaying slower than t^{-n} so that the exponents of the zero modes, ζ_n , grow with n slower than linearly. This is very much like the total energy of the cloud of attracting particles does not grow linearly with the number of particles. Indeed, power-law correlations of the velocity field lead to super-diffusive behavior of inter-particle separations: the farther particles are, the faster they tend to move away from each other, as in Richardson's law of diffusion. That is the system behaves as if there was an attraction between particles that weakens with the distance, though, of course, there is no physical interaction among particles (but only mutual correlations because they are inside the correlation radius of the velocity field). Let us stress that while zero modes of multi-particle evolution exist for all velocity fields—from those that are smooth to those that are extremely rough as in Brownian motion—only those non-smooth velocity fields with power-law correlations provide for an anomalous scaling. Zero modes were discovered in¹⁸⁻²⁰ and then described in.²¹⁻²³

The existence of multi-particle conservation laws indicates the presence of a long-time memory and is a reflection of the coupling among the particles due to the simple fact that they are all in the same velocity field.

We shall now ask: How does the existence of these statistical conservation laws (called martingales in the probability theory) lead to anomalous scaling of fields advected by turbulence? According to (1.20), the correlation functions of θ are proportional to the times spent by the particles within the correlation scales of the pumping. The structure functions of θ are differences of correlation functions with different initial particle configurations

as, for instance, $S_3(r_{12}) \equiv \langle [\theta(\mathbf{r}_1) - \theta(\mathbf{r}_2)]^3 \rangle = 3\langle \theta^2(\mathbf{r}_1)\theta(\mathbf{r}_2) - \theta(\mathbf{r}_1)\theta^2(\mathbf{r}_2) \rangle$. In calculating S_3 , we are thus comparing two histories: the first one with two particles initially close to the position \mathbf{r}_1 and one particle at \mathbf{r}_2 , and the second one with one particle at \mathbf{r}_1 and two particles at \mathbf{r}_2 — see Fig 1.6.. That is, S_3 is proportional to the time during which one can distinguish

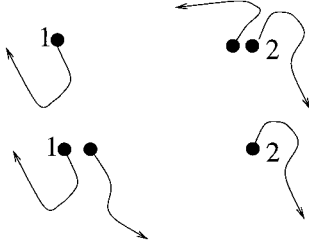


Fig. 1.6. Two configurations (upper and lower) determining the third structure function

one history from another, or to the time needed for an elongated triangle to relax to the equilateral shape. That time decreases as r_{12} grows: the further away the particles, the faster they lose correlations.

Quantitative details can be worked out for the white-in-time velocity¹⁷ (profound insight of Kraichnan was that it is spatial rather than temporal non-smoothness of the velocity that is crucial for an anomalous scaling):

$$\begin{aligned} \langle v^i(\mathbf{r}, t)v^j(0, 0) \rangle &= \delta(t) \left[D_0 \delta_{ij} - d_{ij}(\mathbf{r}) \right], \\ d_{ij} &= D_1 r^{2-\gamma} \left[(d+1-\gamma) \delta^{ij} + (\gamma-2)r^i r^j r^{-2} \right]. \end{aligned} \quad (1.26)$$

Here the exponent $\gamma \in [0, 2]$ is a measure of the velocity nonsmoothness with $\gamma = 0$ corresponding to a smooth velocity, while $\gamma = 2$ corresponds to a velocity which is very rough in space (distributional). Richardson-Kolmogorov scaling of the energy cascade corresponds to $\gamma = 2/3$. Lagrangian flow is a Markov random process for the Kraichnan ensemble (1.26). Every fluid particle undergoes a Brownian random walk with the so-called eddy diffusivity D_0 . The PDF $P(r, t)$ for two particles to be separated by r after time t satisfies the diffusion equation (see e.g.¹⁰)

$$\partial_t P = L_2 P, \quad L_2 = d_{ij}(\mathbf{r}) \nabla^i \nabla^j = D_1 (d-1) r^{1-d} \partial_r r^{d+1-\gamma} \partial_r, \quad (1.27)$$

with the scale-dependent diffusivity $D_1 (d-1) r^{2-\gamma}$. The asymptotic solution of (1.27) is $P(r, t) = r^{d-1} t^{d/\gamma} \exp(-\text{const } r^\gamma / t)$ (lognormal for $\gamma = 0$). For $\gamma = 2/3$, it reproduces, in particular, the Richardson law. Multiparticle probability distributions also satisfy diffusion equations in the Kraichnan

model as well as all the correlation functions of θ . Multiplying (1.18) by $\theta_2 \dots \theta_{2n}$ and averaging over the Gaussian statistics of \mathbf{v} and φ one derives

$$\partial_t F_{2n} = L_{2n} F_{2n} + \sum_{l,m} F_{2n-2} \Phi(\mathbf{r}_{lm}), \quad L_{2n} = \sum d_{ij}(\mathbf{r}_{lm}) \nabla_l^i \nabla_m^j. \quad (1.28)$$

This equation enables one, in principle, to derive inductively all steady-state F_{2n} starting from F_2 . The equation $\partial_t F_2(r, t) = L_2 F_2(r, t) + \Phi(r)$ has a steady solution $F_2(r) = 2[\Phi(0)/\gamma d(d-1)D_1][dL^\gamma/(d-\gamma) - r^\gamma]$, which has the Corrsin-Oboukhov form for $\gamma = 2/3$. Further, F_4 contains the so-called forced solution having the normal scaling 2γ but also, remarkably, a zero mode Z_4 of the operator L_4 : $L_4 Z_4 = 0$. Such zero modes necessarily appear (to satisfy the boundary conditions at $r \simeq L$) for all $n > 1$ and the scaling exponents of Z_{2n} are generally different from $n\gamma$ that is anomalous. In calculating the scalar structure functions, all terms cancel out except a single zero mode (called irreducible because it involves all distances between $2n$ points). Analytical and numerical calculations of Z_n and their scaling exponents σ_n give¹⁰ σ_n lying on a convex curve (see Fig. 1.4.) which saturates²³ to a constant at large n . Such saturation²⁴ is a signature that most singular structures in a scalar field are shocks like in Burgers turbulence, the value σ_n at $n \rightarrow \infty$ is the fractal codimension of fronts in space.

The existence of statistical conserved quantities breaks the scale invariance of scalar statistics in the inertial interval and explains why scalar turbulence knows about pumping “more” than just the value of the flux. Note that both symmetries, one broken by pumping (scale invariance) and another by damping (time reversibility) are not restored even when $r/L \rightarrow 0$ and $r_d/r \rightarrow 0$.

For the vector field (like velocity or magnetic field in magnetohydrodynamics) the Lagrangian statistical integrals of motion may involve both the coordinate of the fluid particle and the vector it carries. Such integrals of motion were built explicitly and related to the anomalous scaling for the passively advected magnetic field in the Kraichnan ensemble of velocities.¹⁰ Doing that for velocity that satisfies the Navier-Stokes equation remains a task for the future.

This course has popular⁷ and technical¹⁰ versions. I am grateful to my co-authors, K. Gawędzki, M. Vergassola and K. Sreenivasan, for teaching me many things. This work was supported by the Israel Science Foundation.

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