

Contents

Preface	v
Chapter 1: Three-Dimensional Theories	1
1.1 Nonlinear Electroelasticity for Strong Fields	1
1.2 Linear Piezoelectricity for Infinitesimal Fields	6
1.2.1 Linearization	6
1.2.2 Polarized ceramics	12
1.2.3 Quartz and langasite	13
1.3 Linear Theory for Small Fields Superposed on a Finite Bias	16
1.3.1 The reference state	16
1.3.2 The initial state	17
1.3.3 The present state	17
1.3.4 Equations for the incremental fields	18
1.3.5 Small bias	20
1.3.6 Frequency perturbation due to a small bias	21
1.4 Cubic Theory for Weak Nonlinearity	22
Chapter 2: Thickness-Shear Modes of Plate Resonators	25
2.1 Static Thickness-Shear Deformation	25
2.1.1 A plate under a mechanical load	25
2.1.2 A plate under an electrical load	28
2.2 Nonlinear Thickness-Shear Deformation	31
2.2.1 General analysis	32
2.2.2. An example	33
2.3 Effects of Initial Fields on Thickness- Shear Deformation	36
2.3.1 General analysis	37
2.3.2 An example	39
2.4 Linear Thickness-Shear Vibration	43
2.4.1 Governing equations	43
2.4.2 Free vibration	45
2.4.3 Forced vibration	47
2.4.4 An unelectroded plate	48

2.5	Effects of Electrode Inertia	49
2.5.1	General analysis	49
2.5.2	Identical electrodes	51
2.6	Inertial Effects of Imperfectly Bounded Electrodes	52
2.6.1	General analysis	52
2.6.2	Identical electrodes	54
2.7	Effects of Electrode Inertia and Shear Stiffness	60
2.7.1	General analysis	60
2.7.2	Special cases	62
2.7.3	Numerical results	64
2.8	Nonlinear Thickness-Shear Vibration	66
2.8.1	Governing equations	66
2.8.2	Free vibration	67
2.8.3	Forced vibration	68
2.9	Effects of Initial Fields on Thickness-Shear Vibration	70
2.9.1	Governing equations	71
2.9.2	Open electrodes	71
2.9.3	Shorted electrodes	72
Chapter 3: Slowly Varying Thickness-Shear Modes		73
3.1	Exact Waves in a Plate	73
3.1.1	Eigenvalue problem	74
3.1.2	An example	77
3.1.3	A special case: Thickness-twist waves in a ceramic plate	78
3.1.4	A special case: Thickness-twist waves in a quartz plate	85
3.2	An Approximate Equation for Thickness-Shear Waves	87
3.3	Thickness-Shear Vibration of Finite Plates	91
3.3.1	Sinusoidal modes	92
3.3.2	Hyperbolic modes	93
3.4	Energy Trapping in Mesa Resonators	93
3.5	Contoured Resonators	97
3.6	Energy Trapping due to Material Inhomogeneity	98
3.6.1	General analysis	98
3.6.2	An example	101
3.7	Energy Trapping by Electrode Mass	103
3.8	Effects of Non-uniform Electrodes	104

3.9	Effects of Electromechanical Coupling on Energy Trapping	106
3.9.1	Governing equations	107
3.9.2	Free vibration solution	108
3.9.3	Discussion	109
3.10	Coupling to Flexure	110
3.10.1	Governing equations	110
3.10.2	Waves in unbounded plates	111
3.10.3	Vibrations of finite plates	112
3.11	Coupling to Face-Shear and Flexure	114
3.11.1	Governing equations	115
3.11.2	Waves in unbounded plates	115
3.11.3	Vibrations of finite plates	117
3.12	Effects of Middle Surface Curvature	119
3.12.1	Governing equations	120
3.12.2	Thickness-shear approximation	122
3.12.3	Coupled thickness-shear and extension	124
Chapter 4: Mass Sensors		127
4.1	Inertial Effect of a Mass Layer by Perturbation	127
4.1.1	Governing equations	127
4.1.2	Abstract notation	128
4.1.3	Perturbation	129
4.2	Thickness-Shear Modes of a Plate	131
4.3	Anti-Plane Modes of a Wedge	132
4.4	Torsional Modes of a Conical Shell	134
4.5	Effects of Inertia and Stiffness of a Mass Layer by Perturbation	135
4.5.1	Governing equations	136
4.5.2	Perturbation	138
4.6	Effects of Inertia and Stiffness of a Mass Layer by Variation	139
4.6.1	Variational formulation	140
4.6.2	Frequency shift	141
4.6.3	Discussion	142
4.7	Radial Modes of a Ring	143
4.7.1	The unperturbed mode	143
4.7.2	Perturbation solution	144
4.7.3	Variation solution	144
4.7.4	Discussion	145

4.8	Effects of Shear Deformability of a Mass Layer	146
4.8.1	Governing equations	147
4.8.2	Variational formulation	150
4.8.3	Frequency shift	151
4.9	Thickness-Shear Modes of a Plate with Thick Mass Layers	153
4.10	An Ill-Posed Problem in Elasticity for Mass Sensors	157
4.10.1	Formulation of the problem	157
4.10.2	Known solutions	158
4.10.3	An open problem	159
4.11	Thickness-Shear Modes of a Circular Cylinder	160
4.11.1	Thickness-shear modes in a circular cylinder	160
4.11.2	Mass sensitivity	161
4.12	Mass Sensitivity of Surface Waves	163
4.12.1	Governing equations	163
4.12.2	A half-space with an electroded surface	165
4.12.3	A half-space with an unelectroded surface	166
4.13	Thickness-Twist Waves in a Ceramic Plate	167
4.13.1	Governing equations	168
4.13.2	Anti-symmetric waves	168
4.13.3	Symmetric waves	170
4.14	Bechmann's Number for Thickness-Twist Waves	171
4.14.1	Thickness-twist waves in an unbounded, unelectroded plate	171
4.14.2	Thickness-twist waves in an unbounded, electroded plate	172
4.14.3	Bechmann's number	173
4.15	Thickness-Twist Waves in a Quartz Plate	175
4.15.1	Symmetric mass layers	175
4.15.2	Asymmetric mass layers	176

Chapter 5: Fluid Sensors **181**

5.1	An Ill-Posed Problem in Elasticity for Fluid Sensors	181
5.1.1	Formulation of the problem	181
5.1.2	Known solutions	182
5.1.3	Boundary integral equation formulation	185
5.1.4	Generalization to piezoelectricity	186
5.2	Perturbation Analysis	187
5.2.1	Governing equations	188
5.2.2	Perturbation analysis	189

5.3	Thickness-Shear Modes of a Plate	191
5.4	Torsional Modes of a Cylindrical Shell	192
	5.4.1 Governing equations	193
	5.4.2 Interior problem	194
	5.4.3 Exterior problem	195
5.5	Thickness-Shear Modes of a Circular Cylinder	196
	5.5.1 Governing equations	196
	5.5.2 Interior problem	197
	5.5.3 Exterior problem	198
	5.5.4 Axial thickness-shear	199
5.6	Surface Wave Fluid Sensors	199
	5.6.1 Governing equations	200
	5.6.2 A half-space with an electroded surface	201
	5.6.3 A half-space with an unelectroded surface	202
5.7	Thickness-Twist Waves in a Ceramic Plate	204
	5.7.1 Governing equations	204
	5.7.2 Anti-symmetric waves	205
	5.7.3 Symmetric waves	206
Chapter 6: Gyroscopes — Frequency Effect		209
6.1	High Frequency Vibrations of a Small Rotating Piezoelectric Body	209
6.2	Propagation of Plane Waves	210
	6.2.1 General solution	210
	6.2.2 Polarized ceramics	215
	6.2.3 Quartz	217
6.3	Thickness Vibrations of Plates	221
	6.3.1 General solution	222
	6.3.2 Ceramic plates	223
	6.3.3 Quartz plates	227
6.4	Propagating Waves in a Rotating Piezoelectric Plate	228
	6.4.1 General solution	228
	6.4.2 Ceramic plates	232
6.5	Surface Waves over a Rotating Piezoelectric Half-Space	236
	6.5.1 General solution	236
	6.5.2 Ceramic half-space	238
Chapter 7: Gyroscopes — Charge Effect		245
7.1	A Rectangular Beam	245

7.1.1	Governing equations	247
7.1.2	Forced vibration solution	250
7.1.3	An example	251
7.2	A Circular Tube	258
7.2.1	Governing equations	260
7.2.2	Forced vibration solution	261
7.2.3	An example	263
7.3	A Beam Bimorph	264
7.3.1	Governing equations	265
7.3.2	Forced vibration solution	270
7.3.3	Free vibration solution	271
7.3.4	An example	272
7.4	An Inhomogeneous Shell	274
7.4.1	Structure	275
7.4.2	Governing equations	276
7.4.3	Forced vibration solution	279
7.4.4	Discussion	282
7.5	A Ceramic Ring	282
7.5.1	Governing equations	284
7.5.2	Free vibration solution	286
7.5.3	Forced vibration solution	287
7.6	A Concentrated Mass and Ceramic Rods	288
7.6.1	Governing equations	289
7.6.2	Forced vibration solution	290
7.7	A Ceramic Plate by Two-Dimensional Equations	291
7.7.1	Driving	292
7.7.2	Sensing	294
7.7.3	Discussion	295
7.8	A Ceramic Plate by Zero-Dimensional Equations	296
7.8.1	Governing equations	297
7.8.2	Free vibration solution	298
7.8.3	Forced vibration solution	299
Chapter 8: Acceleration Sensitivity		301
8.1	Deformation of a Quartz Plate under Normal Acceleration	301
8.1.1	Classical flexure	301
8.1.2	Flexure induced in-plane extension and thickness contraction	303
8.1.3	One-dimensional deformation	305

8.1.4	Two-dimensional deformation	308
8.2	First-Order Acceleration Sensitivity	311
8.3	An Estimate of Second-Order Acceleration Sensitivity and its Reduction	313
8.3.1	An estimate	314
8.3.2	Reduction of normal acceleration sensitivity	315
8.4	Second-Order Perturbation Analysis	318
8.4.1	Relatively large biasing deformations	318
8.4.2	Equations for incremental vibrations	319
8.4.3	Second-order perturbation analysis	321
8.5	Second-Order Normal Acceleration Sensitivity	324
8.5.1	Second-order acceleration sensitivity	325
8.5.2	One-dimensional deformation	326
8.5.3	Two-dimensional deformation	328
8.6	Effects of Middle Surface Curvature	329
8.6.1	Biasing deformation	329
8.6.2	Unperturbed modes	332
8.6.3	Frequency shift	332
8.7	Vibration Sensitivity	334
8.7.1	Governing equations	335
8.7.2	First-order solution	336
8.7.3	Second-order solution	337
8.7.4	An example	338
Chapter 9: Pressure Sensors		341
9.1	A Rectangular Plate in a Circular Cylindrical Shell	341
9.1.1	Analysis	343
9.1.2	Numerical results	345
9.2	A Circular Plate in a Circular Cylindrical Shell	347
9.2.1	Analysis	347
9.2.2	Numerical results	350
9.3	A Rectangular Plate in a Shallow Shell	352
9.3.1	Analysis	352
9.3.2	Numerical results	354
9.4	A Bimorph	355
9.4.1	Analysis	355
9.4.2	Numerical results	358
9.5	Surface Wave Pressure Sensors Based on Extension	361
9.6	Surface Wave Pressure Sensors Based on Flexure	364

9.6.1	Biasing deformations	364
9.6.2	Frequency shifts	368
Chapter 10: Temperature Sensors		371
10.1	Thermoelectroelasticity	371
10.2	Linear Theory	374
10.3	Small Fields Superposed on a Thermal Bias	376
10.4	Thickness-Shear Modes of a Free Plate	379
10.5	Thickness-Shear Modes of a Constrained Plate	382
10.5.1	Analysis	382
10.5.2	An example	385
Chapter 11: Piezoelectric Generators		387
11.1	Thickness-Stretch of a Ceramic Plate	387
11.1.1	Analysis	388
11.1.2	An example	392
11.2	A Circular Shell	395
11.3	A Beam Bimorph	399
11.3.1	Analysis	400
11.3.2	An example	406
11.4	A Spiral Bimorph	407
11.5	Nonlinear Behavior near Resonance	409
11.5.1	Analysis	410
11.5.2	Numerical results	413
Chapter 12: Piezoelectric Transformers		417
12.1	A Thickness-Stretch Mode Plate Transformer	417
12.1.1	Governing equations	417
12.1.2	Analytical solution	419
12.1.3	Numerical results	421
12.2	Rosen Transformer	425
12.2.1	One-dimensional model	425
12.2.2	Free vibration analysis	428
12.2.3	Forced vibration analysis	429
12.2.4	Numerical results	432
12.3	A Thickness-Shear Mode Transformer — Free Vibration	434
12.3.1	Governing equations	435
12.3.2	Free vibration analysis	437
12.3.3	Ceramic transformers	439

12.4	A Thickness-Shear Mode Transformer — Forced Vibration	444
12.4.1	Governing equations	444
12.4.2	Forced vibration analysis	447
Chapter 13: Power Transmissiion through an Elastic Wall		451
13.1	Formulation of the Problem	451
13.2	Theoretical Analysis	454
13.3	Numerical Results	457
Chapter 14: Acoustic Wave Amplifiers		463
14.1	Equations for Piezoelectric Semiconductors	463
14.2	Equations for a Thin Film	464
14.3	Surface Waves	466
14.3.1	Analytical solution	466
14.3.2	Discussion	470
14.3.3	Numerical results	472
14.4	Interface Waves	474
14.4.1	Analytical solution	474
14.4.2	Discussiion	477
14.5	Waves in a Plate	478
14.5.1	Symmetric waves	479
14.5.2	Anti-symmetric waves	482
14.5.3	Discussion	483
14.6	Gap Waves	484
14.6.1	Analytical solution	484
14.6.2	Discussion	487
References		491
Appendix 1 Notation		501
Appendix 2 Electroelastic Material Constants		503
Index		517