

CONTENTS

Preface.....	v
Conference organisers	vi
Conference committees	vii
Conference sponsors and co-sponsors.....	x

Section-1: Plenary Presentations

Development of dance partner robot -PBDR-	3
<i>K. Kosuge</i>	
From micro to nano robotics	5
<i>B. Nelson</i>	
Adhesion techniques for climbing robots: State of the art and experimental considerations	6
<i>D. Longo and G. Muscato</i>	

Section-2: Autonomous Robots

Balance control of a TWRM with a static payload.....	31
<i>K. M. K. Goher and M. O. Tokhi</i>	
Balance control of a TWRM with a dynamic payload	39
<i>K. M. K. Goher and M. O. Tokhi</i>	
A cooperative climbing robot for melt weld inspection on large structures	47
<i>J. Shang, S. Mondal, A. A. Brenner, B. Bridge and T. Sattar</i>	
Power analysis and structure optimization in the design of a humanoid robot	55
<i>L. Wang, M. Xie, Z. W. Zhong, M. Wang and L. Zhang</i>	
Detection and clustering of the erroneous torques developed in the femur joint of a walking robot.....	63
<i>A. Vitko, L. Jurišica, M. Klučik, R. Murár and F. Duchoň</i>	

A modular mobile self-reconfigurable robot	71
<i>M. Zhong, P. Wang, M. Li and W. Guo</i>	
Localizing from multi-hypotheses states minimizing expected path lengths for mobile robots.....	79
<i>K. Hemanth, S. Subhash, K. M. Krishna and A. K. Pandey</i>	
Design of new modular walking robot MERO	87
<i>I. Ion, I. Simionescu, A. Curaj, V. Luige and A. Vasile</i>	
Behavior network control for a holonomic mobile robot in realistic environments.....	98
<i>M. Göller, T. Kerscher, J. M. Zöllner and R. Dillmann</i>	
RFID transponder barriers as artificial landmarks for the semantic navigation of autonomous robots	106
<i>M. Göller, F. Steinhardt, T. Kerscher, J. M. Zöllner and R. Dillmann</i>	
Development of predictive models of climbing robot attachment mechanisms for an energy-efficient adaptive control scheme	114
<i>S. A. Jacobs and A. A. Dehghani-Sanij</i>	
Merging topological maps for localisation in large environments.....	122
<i>F. Ferreira, J. Dias and V. Santos</i>	
Section-3: Benchmarking and Standardization	
ISO standards for service robots	133
<i>G. S. Virk, S. Moon and R. Gelin</i>	
The replication of experiments and the performance evaluation in Clawar system research	139
<i>F. P. Bonsignorio</i>	
A scalable benchmark for motion control of mobile robots	146
<i>A. Marjovi and L. Marques</i>	
Benchmarking of the robot design process.....	154
<i>G. S. Virk</i>	

Section-4: Biologically-Inspired Systems and Solutions

A neural network architecture for progressive learning of robotic grasps	165
<i>J. Molina-Vilaplana and J. Lopez-Coronado</i>	
GRACE – Generic robotic architecture to create emotions.....	174
<i>T. H. H. Dang, S. L. Zarshenas and D. Duhaut</i>	
Biomimetic approach for tortoise-like robot modeling and control	182
<i>H. El Daou, J.-C. Guinot, P.-A. Libourel, S. Renous and V. Bels</i>	
Application of smart materials – Bionics modular adaptive implant.....	190
<i>N. G. Bîzdoacă, D. Tarniță, D. Tarniță and E. Bîzdoacă</i>	
Kinematics and kinetics analysis of rectilinear locomotion gait.....	198
<i>A. Ghanbari, A. Rostami, S. M. R. S. Noorani and M. M. S. Fakhrabadi</i>	
INSPIRAT – Towards a biologically inspired climbing robot for the inspection of linear structures.....	206
<i>J. Maempel, E. Andrada, H. Witte, C. Trommer, A. Karguth, M. Fischer, D. Voigt and S. N. Gorb</i>	
Control of the multi-track type robot inspired from antennae of a centipede.....	214
<i>T. Chung, K. H. Hyun, C.-K. Woo, S. Kim and Y. K. Kwak</i>	
Implementation of analog controller based on biological nervous system for biomimetics walking robot.....	221
<i>S. H. Kim, T. H. Kang and J.-H. Cho</i>	
On the design of walking machines using biarticulate actuators	229
<i>T. J. Klein, T. M. Pham and M. A. Lewis</i>	
Modelling and design of IPMC devices	238
<i>I. Chochlidakis, G. S. Virk and A. Dehghani-Sanji</i>	
Analysis, simulation and implementation of a human inspired pole climbing robot	247
<i>A. Sadeghi, H. Moradi and M. N. Ahmadabadi</i>	

A comparison study on pneumatic muscles and electrical motors using the 3DCLIMBER as a case study	255
<i>M. Tavakoli, L. Marques and A. T. de Almeida</i>	

Section-5: Biomedical Robotic Assistance

Impact of upper body effort in FES-assisted indoor rowing exercise.....	265
<i>Z. Hussain, M. O. Tokhi and S. Gharooni</i>	
GA-tuned fuzzy logic control for FES-assisted indoor rowing exercise.....	274
<i>Z. Hussain, M. O. Tokhi, S. Ahmad and S. F. Toha</i>	
Compliant control of FES-rowing with energy store and release mechanism.....	282
<i>S. Sareh, B. J. Andrews, S. Gharooni and M. O. Tokhi</i>	
An electrode array design for use with a multichannel functional electrical stimulator	289
<i>N. Sha, L. P. Kenney, D. Howard, M. Moatamedi, B. Heller and A. T. Barker</i>	
Body-weight-supported treadmill locomotion with spring brake orthosis.....	294
<i>M. S. Huq and M. O. Tokhi</i>	

Section-6: Climbing, Guidance and Navigation

Structure and model identification of a vortex-based suction cup.....	303
<i>F. Bonaccorso, C. Bruno, D. Longo and G. Muscato</i>	
CROMSCI - A climbing robot with multiple sucking chambers for inspection tasks	311
<i>C. Hillenbrand, D. Schmidt and K. Berns</i>	
Magnetic wheeled robot with high mobility but only 2 DOF to control.....	319
<i>W. Fischer, F. Tâche, G. Caprari and R. Siegwart</i>	
A climbing rescue robot	329
<i>L. Rimassa, M. Zoppi and R. Molfino</i>	

Evolution and perspectives of climbing robots at the industrial automation institute. Lessons learned and new directions 337
M. A. Armada, T. Akinfiyev, R. Fernandez, P. González de Santos, E. García, S. Nabulsi, H. Montes, J. C. Grieco and G. Fernandez

Efficient sensor-based path planning for landmine location using walking robots 345
A. Ramos, E. Garcia and P. Gonzalez de Santos

Sniffing a fire: Simulated experiments in a reduced scale scenario 353
P. Oliveira, L. Marques and A. T. de Almeida

Section-7: Flexible Mechanisms for Mobile Machines

Rolling locomotion of a deformable soft robot with built-in power source 365
Y. Matsumoto, H. Nakanishi and S. Hirai

Jumping via robot body deformation — Mechanics and mechanism for higher jumping 373
M. Miyazaki and S. Hirai

Augmented control scheme for input tracking and vibration suppression of flexible manoeuvring systems: Experimental investigations 381
F. M. Aldebrez and M. O. Tokhi

A robotic catapult based on the closed elastic a with a high stiffness endpoint and its application to impulsive swimming robot 389
M. Watari, A. Yamada, H. Mochiyama and H. Fujimoto

A robotic catapult based on the closed elastica with an anisotropic stiffness point and its application to compact continuous jumping robot 397
A. Yamada, M. Watari, H. Mochiyama and H. Fujimoto

Quasi-static energy analysis of the robotic catapult based on the closed elastica 405
H. Mochiyama, A. Yamada and H. Fujimoto

Section-8: Flexible Maneuvering Systems

Modelling and control of an overhead crane with 3DOF	415
<i>O. A. A. Shaebi and M. O. Tokhi</i>	
Impact of the hook attachment mechanism on control of an overhead crane	423
<i>O. A. A. Shaebi and M. O. Tokhi</i>	
Genetic algorithm optimization of PID controller for a flexible manipulator	431
<i>B. A. M. Zain and M. O. Tokhi</i>	
Genetic optimisation of ANFIS network for modelling of a TRMS.....	439
<i>S. F. Toha, M. O. Tokhi and Z. Hussain</i>	
Control of a single - link flexible arm to be used as a sensing antenna	447
<i>J. G. Fernández and V. F. Battle</i>	
Augmented control scheme for input tracking and vibration suppression of flexible manoeuvring systems: Simulation studies.....	455
<i>F. M. Aldebrez and M. O. Tokhi</i>	
Output feedback nonlinear model predictive control of a twin rotor MIMO system	463
<i>A. Rahideh and M. H. Shaheed</i>	
Section-9: Human-Machine Interface, Tele-Presence and Virtual Reality	
Intuitive human-robot cooperation	473
<i>H. Woern and A. J. Schmid</i>	
The influence of human factors on task performance: A linear approach	481
<i>Y. Gatsoulis, G. S. Virk and A. A. Dehghani</i>	
Brain computer interface approaches to control mobile robotic devices.....	489
<i>G. Pires, U. Nunes and M. Castelo-Branco</i>	
Stereo camera based head orientation estimation for real-time system	497
<i>Y.-O. Kim and S. Jun</i>	

Humanoid robot game: A mixture of vr and teleoperation 506
T. Juhász and L. Vajta

EXOSTATION: 7-DOF haptic control chain featuring an arm
 exoskeleton and virtual reality tools 514
*P. Letier, M. Avraam, S. Veillerette, M. Horodincu, A. Preumont,
 J.-P. Verschueren, E. Motard and L. Steinicke*

Section–10: Innovative Design of CLAWAR

Dexterous energy-autarkic climbing robot 525
W. Brockmann, S. Albrecht, D. Borrmann and J. Elseberg

Wall climbing robotic system and noise control for
 reconnaissance purpose 533
P. Wang, M. Li, W. Li and M. Zhong

Design of climbing cleaning robot for vertical surfaces 541
T. Akinfiyev, M. Armada and S. Nabulsi

Design of wheeled climbing robot with changeable structure 549
T. Akinfiyev, R. Fernandez and M. Armada

Climbing ring robot for inspection of offshore wind turbines 555
H. Leon-Rodriguez, B. Bridge and T. P. Sattar

Section–11: Inspection and Non-Destructive Testing

On the mechanized inspection of glass fiber plastic pipes and pipe joints 565
*P. Chatzakos, A. Lagonikas, D. Psarros, V. Spais,
 K. Hrissagis and A. Khalid*

Remote automated non-destructive testing (NDT) weld inspection
 on vertical surfaces 573
S. C. Mondal, A. A. Brenner, J. Shang, B. Bridge and T. P. Sattar

Can semantics help autonomous service robots in inspecting
 complex environments? 581
*M. Ziegenmeyer, K. Uhl, S. Sayler, B. Gassmann,
 J. M. Zöllner and R. Dillmann*

Robotic system for inspection of test objects with unknown geometry using NDT methods.....	589
<i>A. A. Brenner and T. P. Sattar</i>	
A proposed wall climbing robot for oil tank inspection	597
<i>R. Fernández-Rodríguez, V. Feliu and A. González-Rodríguez</i>	
Underwater wall climbing robot for nuclear pressure vessel inspection.....	605
<i>H. E. Leon-Rodriguez, T. Sattar and J. Shang</i>	
Amphibious inspection robot	613
<i>T. P. Sattar, H. E. Leon-Rodriguez and J. Shang</i>	

Section-12: Locomotion

Stable upright walking and running using a simple pendulum based control scheme	623
<i>H. M. Maus, J. Rummel and A. Seyfarth</i>	
From biomechanical concepts towards fast and robust robots	630
<i>D. Renjewski, A. Seyfarth, P. Manoonpong and F. Wörgötter</i>	
From hopping to walking-how the biped Jena-walker can learn from the single-leg Marco-hopper	638
<i>K. T. Kalveram, D. Häufle and A. Seyfarth</i>	
Initiating normal walking of a dynamic biped with a biologically motivated control.....	646
<i>T. Luksch and K. Berns</i>	
Motion design for an insectomorphic robot on unstable obstacles.....	654
<i>Y. F. Golubev and V. V. Korianov</i>	
The effect of leg segmental proportions on the energetic cost of robotic locomotion	662
<i>P. Chatzakos and E. Papadopoulos</i>	
Sliding mode attitude control of a six-legged robot in consideration of actuator dynamics	671
<i>H. Uchida and K. Nonami</i>	

Generation method of feedback control input of leg link using an attitude sensor for a six legged robot consisting of one link.....	679
<i>H. Uchida, Y. Shimizu and S. Nakayama</i>	
Simple intuitive method for a planar biped robot to walk	687
<i>G. Chung</i>	
Obstacle avoidance strategy for biped robot based on fuzzy q-learning	695
<i>C. Sabourin, K. Madani, W. Yu and J. Yan</i>	
Adaptive locomotion for a hexagonal hexapod robot based on a hierarchical Markov decision process	703
<i>G. Cuaya-Simbro and A. Muñoz-Meléndez</i>	
Walking gait control for making smooth locomotion mode change of a legged and wheeled robot.....	711
<i>T. Okada, W. T. Botelho and T. Shimizu</i>	
The DLR-crawler: Gaits and control of an actively compliant hexapod	720
<i>M. Goerner and G. Hirzinger</i>	
Developing fast bipedal locomotion method for inclined floors	728
<i>A. Eshghinejad and M. Keshmiri</i>	
Behaviour-based control of the six-legged walking machine LAURON IVc	736
<i>T. Kerscher, A. Roennau, M. Ziegenmeyer, B. Gassmann, J. M. Zoellner and R. Dillmann</i>	
Particle swarm optimization for humanoid walking-gaits generation.....	744
<i>N. Rokbani, E. Ben Boussada and A. M. Alimi</i>	
Mechanism for variable transformation shapes of a single-tracked mobile structure.....	752
<i>J. Kim and C. Lee</i>	
Optimal posture control for force actuator based articulated suspension vehicle for rough terrain mobility	760
<i>V. P. Eathakota, S. Kolachalama, K. M. Krishna and S. Sanan</i>	

Adaptive stair-climbing behaviour with a hybrid legged-wheeled robot	768
<i>M. Eich, F. Grimminger and F. Kirchner</i>	
Stability control of a hybrid wheel-legged robot using the potential field approach.....	776
<i>G. Besseron, Ch. Grand, F. Ben Amar and Ph. Bidaud</i>	
Logic-based automatic locomotion mode control of a wheel-legged robot.....	784
<i>I. Leppänen, P. Virekoski and A. Halme</i>	
Section–13: Manipulation and Gripping	
Motion planning to catch a moving object	795
<i>J. Serrano, C. Pérez, R. Morales, N. García, J. M. Azorín and J. M. Sabater</i>	
Teleoperation of a manipulator with a master robot of different kinematics: Using bilateral control by state convergence.....	804
<i>C. Peña, R. Aracil, R. Saltaren, I. Banfeld and J. M. Sabater</i>	
Influence of the sampling strategy on the incremental generation of the grasp space	812
<i>M. A. Roa, R. Suarez and J. Rosell</i>	
Robot-human cooperation holding and handling a piece of fabric	820
<i>P. N. Koustoumpardis and N. A. Aspragathos</i>	
A sub €1000 robot hand for grasping — Design, simulation and evaluation	828
<i>J. E. Tegin, J. Wikander and B. Iliev</i>	
Improving manipulation capabilities by means of radio frequency identification and computer vision	836
<i>J. Sales, X. García, P. J. Sanz, R. Marin, M. Prats and Z. Falomir</i>	
A cooperative gripper for handling and hanging limp parts	843
<i>E. Carca, M. Zoppi and R. Molfino</i>	
Robust grasping of 3D objects with stereo vision and tactile feedback.....	851
<i>B. J. Grzyb, E. Chinellato, A. Morales and A. P. del Pobil</i>	

Bond graph modeling of soft contact for robotic grasping.....	859
<i>A. Khurshid and A. Ghafoor</i>	
Optimum size of a soft-finger contact in robotic grasp	867
<i>A. Ghafoor and J. S. Dai</i>	
Tactile sensing methods for automated blood samples on humans	875
<i>A. S. Sørensen, T. R. Savarimuthu, E. Pedersen and A. G. Buch</i>	

Section–14: Modeling and Simulation of CLAWAR

Study of a vibration driven hopping robot.....	893
<i>S. Jatsun, V. Dyshenko and A. Yatsun</i>	
Computational cost of two forward kinematic models for a S-G based climbing robot.....	902
<i>M. Almonacid, R. Saltaren, R. Araci, C. Perez, N. Garcia, J. M. Azorin and J. M. Sabater</i>	
RobuDOG's design, modelling and control	911
<i>P. Bidaud, S. Barthélemy, P. Jarrault, D. Sallé and É. Lucet</i>	
Walking robot “ANTON”: Design, simulation, experiments	922
<i>M. Konyev, F. Palis, Y. Zavgorodniy, A. Melnikov, A. Rudskiy, A. Telesh, U. Schmucker and V. Rusin</i>	
A nonlinear model for simulating contact and collision	930
<i>D. A. Jacobs and K. J. Waldron</i>	
Using nonlinear oscillators to create a pattern generator of bipedal locomotion.....	937
<i>A. C. de Pina Filho and M. S. Dutra</i>	
Internet 3.0 for the simulation of networked clawar systems.....	945
<i>F. P. Bonsignorio</i>	

Section–15: Perception, Sensing and Sensor Fusion

Application of lateral obstacle sensor in following contours for terrain recognition tasks	955
<i>R. Ponticelli and P. Gonzalez de Santos</i>	

True ground speed measurement, a novel optical approach	963
<i>V. Kálmán and T. Takács</i>	
Simple optoelectronic exteroceptive sensor for the control of the dynamic equilibrium of a walking robot.....	971
<i>E. Král</i>	
Analysing human-robot interaction using omni-directional vision and structure from motion	977
<i>C. Salinas and M. A. Armada</i>	
Six DOF sensory system for the force-torque control of walking humanoid	985
<i>M. Kvasnica</i>	
kheNose - A smart transducer for gas sensing.....	993
<i>J. Pascoal, P. Sousa and L. Marques</i>	

Section–16: Personal Assistance

FES-assisted cycling with quadriceps stimulation and energy storage	1003
<i>B. S. K. K. Ibrahim, S. C. Gharooni, M. O. Tokhi and R. Massoud</i>	
Modelling and simulation of sit-to-stand in humanoid dynamic model.....	1011
<i>S. C. Gharooni, M. Joghtaei and M. O. Tokhi</i>	
A new gravity compensation system composed of passive mechanical elements for safe wearable rehabilitation system	1019
<i>T. Nakayama, T. Asahi and H. Fujimoto</i>	
A robotic walker with standing, walking and seating assistance	1027
<i>D. Chugo, T. Asawa, T. Kitamura and K. Takase</i>	
Step climbing of a four-wheel-drive omnidirectional wheelchair.....	1035
<i>M. Wada</i>	
Steering control of wheelchair on two wheels	1043
<i>S. Ahmad, M. O. Tokhi and K. M. K. Goher</i>	

Section–17: Planetary Exploration and Localization

- Development of an underground explorer robot based on an earthworm’s peristaltic crawling 1053
H. Omori, T. Nakamura and T. Yada
- Mechanical and electrical design of a two segmental eight-legged mobile robot for planetary exploration..... 1061
B. Ugurlu, C. M. Uzundere, H. Temeltas and A. Kawamura
- Visual odometry technique using circular marker identification for motion parameter estimation 1069
S. Chhaniyara, K. Althoefer and L. D. Seneviratne

Section–18: Planning and Control

- Single view depth estimation based formation control of robotic swarms: Implementation using realistic robot simulator 1079
V. Gazi, B. Fidan and S. Zhai
- Mechanical design and motion planning of a modular reconfigurable robot 1090
A. H. H. A. Memar, P. Z. H. Bagher and M. Keshmiri
- Approximation control of a differential-drive mobile robot..... 1098
H. Marin-Reyes and M. O. Tokhi
- Experimental study on track-terrain interaction dynamics in an integrated environment: Test rig..... 1106
S. Al-Milli, S. Chhaniyara, E. Georgiou, K. Althoefer, J. S. Dai and L. Seneviratne
- A step toward autonomous pole climbing robots 1114
M. Tavakoli, A. Marjovi, L. Marques and A. T. de Almeida

Section–19: Service Robots

- Development of the riding robot like as a horse and motion control for the healthcare and entertainment..... 1125
M. Lim and J. Lim

Climbing robots: A survey of technologies and applications	1133
<i>M. F. Silva and J. A. T. Machado</i>	
UNIFIER – Unified robotic system to service solar power plants	1141
<i>R. Azaiz</i>	
A feasibility study for energy autonomy in multi robot search and rescue operations.....	1146
<i>Y. Sindi, T. Pipe, S. Dogramadzi, A. Winfield and C. Melhuish</i>	
Person following with a mobile robot using a modified optical flow	1154
<i>A. Handa, J. Sivaswamy, K. M. Krishna, S. Singh and P. Menezes</i>	
Development of a simulation environment of an entertainment humanoid robot doing a handstand on a high bar.....	1161
<i>P. Teodoro, M. A. Botto, C. Cardeira, J. Martins, J. sá da Costa and L. Schweitzer</i>	
Section–20: Workshop on Humanoid Robotics	
Selecting and learning multi-robot team strategies.....	1171
<i>M. M. Veloso</i>	
Fractional calculus: Application in control and robotics	1172
<i>J. A. T. Machado</i>	
Development and gait generation of the biped robot stepper-senior	1173
<i>Y. Liu, M. Zhao, J. Zhang, L. Li, X. Su and H. Dong</i>	
A deterministic way of planning and controlling biped walking of LOCH humanoid robot.....	1181
<i>M. Xie, Z. W. Zhong, L. Zhang, L. B. Xian, L. Wang, H. J. Yang, C. S. Song and J. Li</i>	
Inverse dynamics modelling for humanoid robots based in Lie groups and screws	1191
<i>M. Arbulu and C. Balaguer</i>	
Human-humanoid robot cooperation in collaborative transportation tasks	1199
<i>M. Arbulu and C. Balaguer</i>	

A convex optimization approach for online walking pattern generation	1207
<i>R. Xiong, C. Zhou, L. Zhang and J. Chu</i>	
Energy-efficient humanoid walking with ankle actuation: Learning from biomechanics	1216
<i>R. Versluys, B. Vanderborght, R. Van Ham, P. Beyl, P. Cherelle and D. Lefeber</i>	
A fall down resistant humanoid robot with soft cover and automatically recoverable mechanical overload protection	1225
<i>M. Hayashi, R. Ueda, T. Yoshikai and M. Inaba</i>	
Retargeting system for a social robot imitation interface	1233
<i>J. P. Bandera, R. Marfil, R. López, J. C. del Toro, A. Palomino and F. Sandoval</i>	
Realistic humanoid robot simulation with an optimized controller: A power consumption minimization approach	1242
<i>J. L. Lima, J. C. Gonçalves, P. J. Costa and A. P. Moreira</i>	
A Lie group formulation for realtime ZMP detection using force/torque sensor	1250
<i>L. Zhang, C. Zhou and R. Xiong</i>	
Visual tracking on an autonomous self-contained humanoid robot	1258
<i>M. Rodrigues, F. Silva and V. Santos</i>	
Pose estimation for grasping preparation from stereo ellipses	1266
<i>G. Saponaro and A. Bernardino</i>	
Author index.....	1275